10th UTC Spotlight Conference Pedestrian and Bicycle Safety

Understanding Cyclist Violations at Intersections Using Naturalistic Cycling Data

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Research Question

 How to prevent/mitigate these intersectionrelated crashes resulted from bicycle violations?

- Therefore,
 - The failure to comply needs to be predicted.

Data and methods

• The experiment was conducted in three steps; prescreening, data collection and Data reduction

Mini-DAS includes: Forward view Ca Rider view Can Accelerometer Gyroscope GPS Speed sensor	amera	Mini-DAS Removable Battery Image: State	na Dana balan Martin and tanan Martin and tanan Tanan Tanan National Martin Mar		Control Templet Cont
No		Variable	No	Variable	
	1	Movement type (right/through/left)	6	Weather 1(warm/cool)	- And And Ar
	2	presence of other road users(side/opposing/front/adjacent)	her road 7 Weather front/adjacent) 7 2(cloudy/rainy/clear)		N of Yolkes
	3	Time 1 (morning/noon/evening)	8	yellow onset]
	4	Time 2 (weekend/weekday)	9	red onset	
	5	Road slope (uphill/downhill/flat)			

Results Statistical Analysis

- mixed effects generalized regression model was used
- Signalized intersection,
 - It was found that a cyclist is more likely to violate a red light when making right turns.
 - Besides, the probability of a red light violation decreases when there is side traffic at the intersection or when there is an opposing traffic to the cyclist
- Stop-controlled intersections
 - It was found that right turn, left turn and warm weather are significant factors.
 - Moreover, the likelihood of a stop sign violation increases when no other users are present.

Predicting intersection violations by cyclists

Factor Prediction is ca celeration, mean(TTI) over the t_{mon}^{ν} ough time for time to intersed the endangered range(TTI) over the t_{mon}^{v} t_{min}^{v} is equivale driver/rider std(TTI) over the t_{mon}^{v} to react (i.e., $t_{d_1}^e$ ldangered max(TTI) over the t_{mon}^{ν} min(TTI) over the t_{mon}^{ν} t_{dri} twmon ······ mean(speed) over the t_{mon}^{ν} endangered range(speed) over the t_{mon}^{v} vehicle/bicycle iolating std(speed) over the t_{mon}^{ν} max(speed) over the t_{mon}^{ν}

Results Predictive Analysis

- Model Comparison
 - The overall accuracy (ACC), true positive rate (TP) and false positive rate (FP)

	ACC	ТР	FP
RF	99.09	99.47	3.33
KNN(k=7)	89.44	97.33	41.33
ANN	91.74	97.37	29.83
Logistic regression	91.28	95.37	33.00

Limitation of this work

- The data collection was conducted in Virginia and most observations were in the small town of Blacksburg.
- Since violations are rare events, collecting more data would also be useful to obtain violation behavior for different types of violations.