

Impact assessment of autonomous Demand Responsive transport (DRT) systems

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mobil.TUM 2018

Motivation

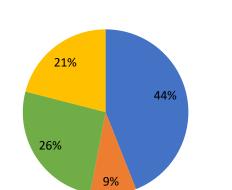
- Developments in AV technology may sooner or later lead to new taxi-like services using Shared Autonomous Vehicles
- But what's the impact on smaller cities?
 - City of Cottbus as an example
- City of 100 000 inhabitants in Southern Brandenburg
 - Roughly 100km SE of Berlin
- Germany's smallest *metropolitan area,* 80th biggest city by population size





Transport in Cottbus

- Public transport network consists of
 - 5 tram lines
 - 11 bus lines
- Headways of 20-30 minutes during weekdays, with reduced frequency during nighttimes and on weekends
- Modal share of public transport is rather low
- Roughly pt 30 000 trips per day
- Most distances can easily covered by bike and walk
- City does not suffer from congestion







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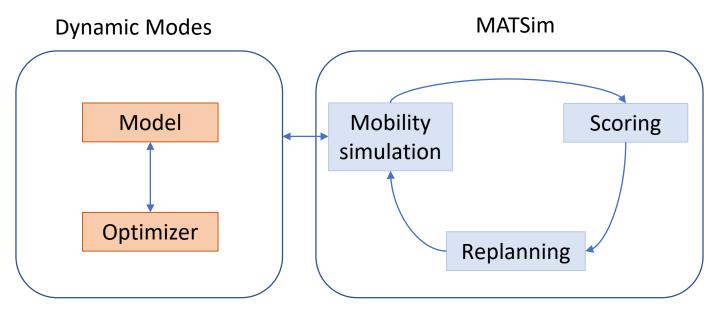
SAVs and public transport | Joschka Bischoff page 3

Modal Split in Cottbus (2008)

Methodology: MATSim



- MATSim allows the simulation of agents along their daily activity chains
- Open source, written in JAVA and well-documented
- Multiple iterations with behavioral changes in between allow agents to maximize their utility
- Dynamic modes, such as (shared) taxis directly operate within the traffic simulation runtime





Simulation experiments

- Based on an existing multi-modal MATSim model for Cottbus
- Reference year 2010
- Three diferent experiments:
- 1. Base Case:
 - Uses current public transport Schedule
- 2. Door to Door Scheme
 - DRT vehicles pick up and drop off passengers at their activity locations
- 3. Stop based service
 - Passengers need to walk to and from designated stops
 - 400 Stops clustered using k-means approach
- Eight seat vehicles, No pre-bookings of vehicles, maximum detour of 1.5x direct trip, less than 1 % of trips should be rejected



Results: Fleet size

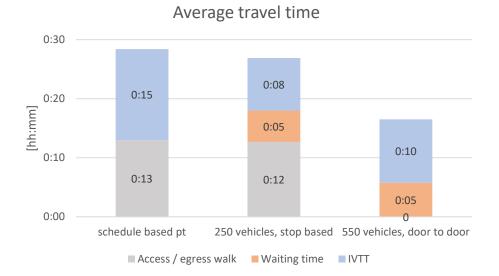
- Based on the defined service criteria:
 - 550 vehicles for door to door service
 - 250 vehicles for stop based service

(Current fleet: 48 busses, 21 trams)



Travel times

- Per person travel times may be significantly reduced
- In vehicle travel time reduces by 50 %
- Average waiting time for DRT vehicles of around 5 minutes
- Stop based mode: Vehicle is only called once passenger reaches stop → Room for improvement
- Waiting time of pt trips neglected (including for transfers) in figure below





Cost analysis

- Cost models for SAV are available
- Based on Bösch, et al, 2017: 0.25 € / pkm (incl. procurement)
- For public transport: 2,38 €/ km (operational value from Potsdam; pure operational costs)



Daily operational costs



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Conclusion

- Automated Demand Responsive Transport may be a viable alternative to Schedule based public transport systems in smaller cities
- DRT systems will reduce travel times for a majority of users
- Their operation may be cheaper than classical transport systems in those areas, if stops are used for bundling
- A combination of stops and door to door may increase ridership even further
- Mode choice experiments should be made



Thank you for your attention! Questions?



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SAVs and public transport | Joschka Bischoff page 10