

Enhancing Safety Through Automation

TRB Automated Vehicle Workshop, July 25, 2012

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Research

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NHTSA's Missions



■ Safety

Save lives, prevent injuries and reduce economic costs due to road traffic and non-traffic crashes through education, research, safety standards and enforcement activity.

■ Consumer Programs

Increase fuel economy, damageability protection, and theft protection, reduce odometer tampering, and provide consumer information.

The Problem!!!



Safety

- 32,788 highway deaths in 2010
- 6,000,000 crashes/year
- Leading cause of death for ages 4 - 34



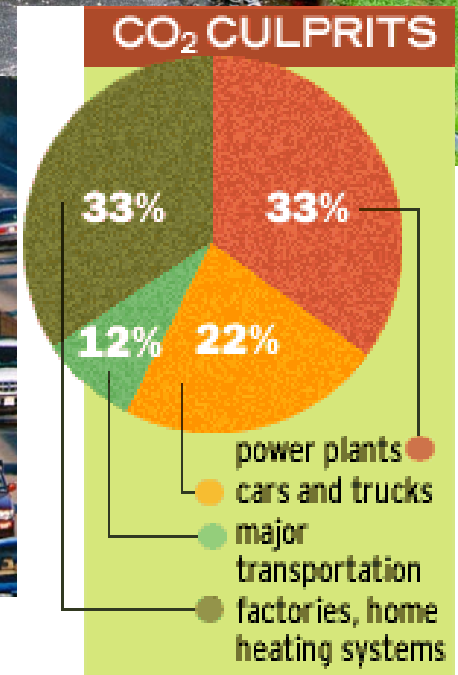
Mobility

- 4,200,000,000 hours of travel delay
- \$80,000,000,000 cost of urban congestion

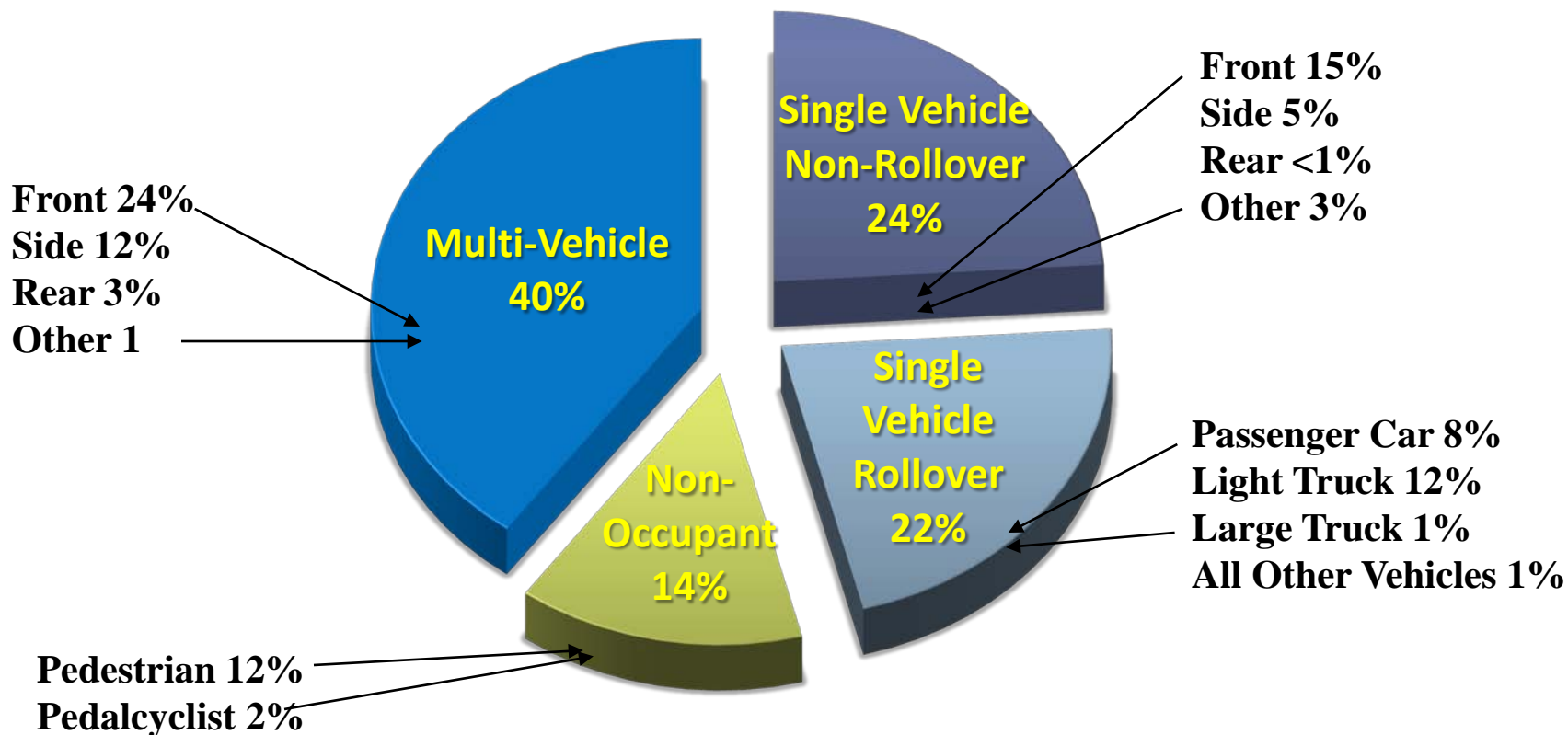


Environment

- 2,900,000,000 gallons of wasted fuel



Fatalities in Motor Vehicle Traffic Crashes 2009



Human Error is Critical Reason for 93% of Crashes

Crash Avoidance

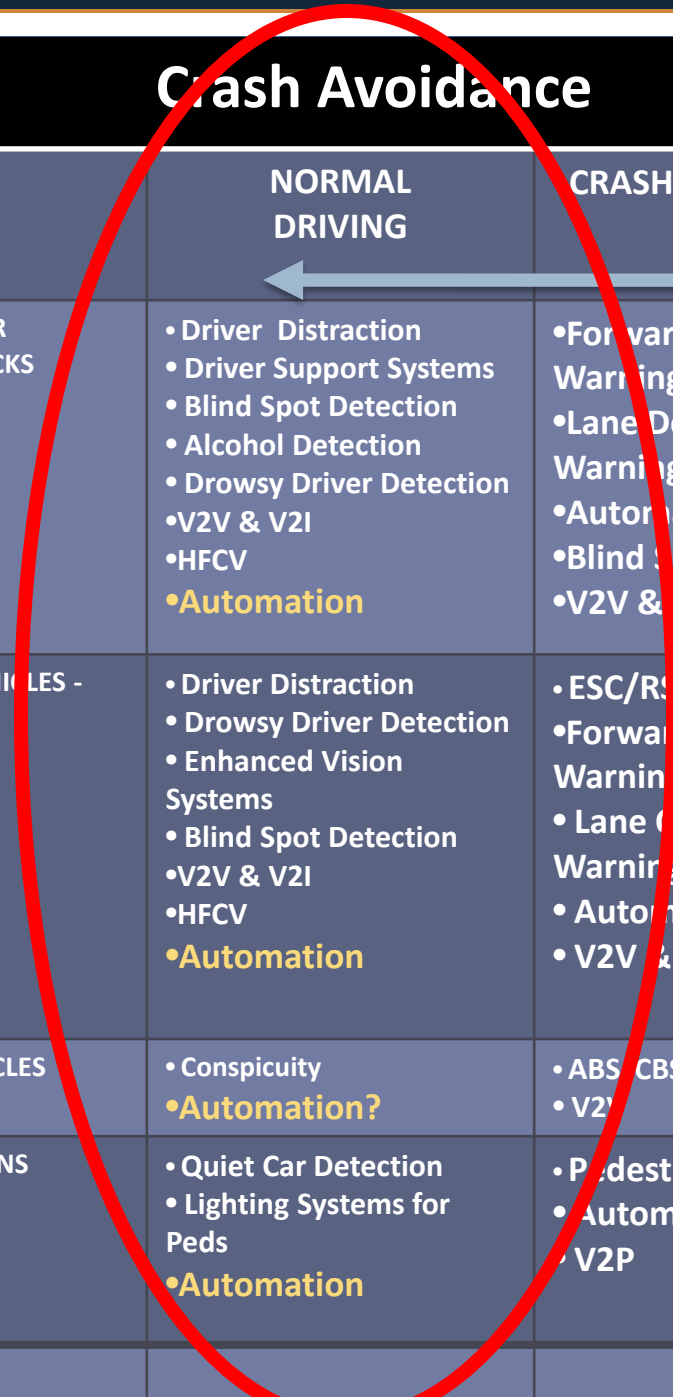
Crashworthiness

	NORMAL DRIVING	CRASH IMMINENT	CRASH EVENT	POST-CRASH
PASSENGER CARS/TRUCKS	<ul style="list-style-type: none"> • Driver Distraction • Driver Support Systems • Blind Spot Detection • Alcohol Detection • Drowsy Driver Detection • V2V & V2I • Human Factors/HMI • Automation 	<ul style="list-style-type: none"> • Forward Crash Warning • Lane Departure Warning • Lane Keeping • Lane change/Blind Spot • Automatic Braking • Connected Vehicles [Vehicle-to-Vehicle (V2V) Communication] 	<ul style="list-style-type: none"> • Dynamic Rollover • Oblique/Off-set Frontal • Adaptive Restraints • Child Side Impact • Elderly Occupants • 	<ul style="list-style-type: none"> • Auto Crash Notification • Advanced ACN • Medical Outcome (CIREN) • First Responder Safety
HEAVY VEHICLES - Truck/Bus	<ul style="list-style-type: none"> • Driver Distraction • Drowsy Driver Detection • Enhanced Vision Systems • Blind Spot Detection • V2V & V2I • Human Factors/HMI • Automation 	<ul style="list-style-type: none"> • ESC/RSC • Forward Collision Warning • Lane Change Warning • Automatic Braking • Lane Keeping • V2V 	<ul style="list-style-type: none"> • Underride 	
MOTORCYCLES	<ul style="list-style-type: none"> • Conspicuity • Automation? 	<ul style="list-style-type: none"> • ABS/CBS • V2V 	<ul style="list-style-type: none"> • Helmet Use • Airbags 	<ul style="list-style-type: none"> • ACN
PEDESTRIANS	<ul style="list-style-type: none"> • Quiet Car Detection • Lighting Systems for Peds • Automation 	<ul style="list-style-type: none"> • Pedestrian Warning • Automatic Braking • V2P 	<ul style="list-style-type: none"> • GTR – Hoods / Bumpers 	<ul style="list-style-type: none"> • ACN

Crash Avoidance

Crashworthiness

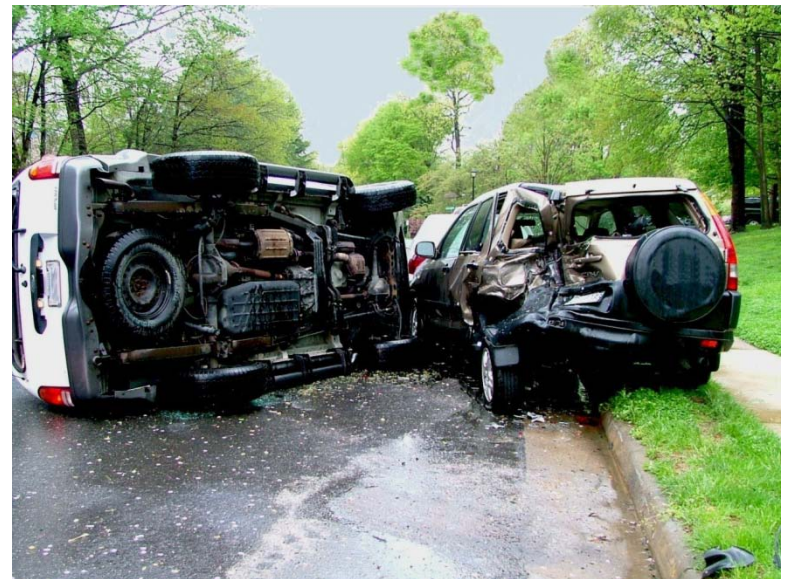
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Focus on Safety



- Automation should be focused first on safety
- Not enough to be “as safe” as human drivers
- Automated car goal: “crash-less”



Definitions are Important



■ Autonomous

- “not subject to control from outside; independent” *
- “undertaken or carried on without outside control” #

■ Automated

- “automatically controlled operation of an apparatus, process or system by mechanical or electronic devices that take the place of human labor” #

■ Cooperative

- “acting together for a common purpose or benefit” *

Sources: * <http://dictionary.reference.com>

<http://www.merriam-webster.com/dictionary>

Levels of Automation (NHTSA Draft)



	Monitoring Roadway	Active Control	Responsibility for Safe Operation	Driver/Occupant Availability
Level 0 - Non-Automated	D	D	D	Y
Level 1 - Automated-Assisted	D	D and R	D	Y
Level 2 - Monitored Automation	D	R	D	Y
Level 3 - Conditional Automation	R	R	R?	Y
Level 4 - Full Automation	R	R	R?	N
D= Driver				
R= Robot				

Building Blocks for Autonomous Operation



Automated Operation

Policy Considerations

Infrastructure Changes?

Active Driver Engagement?

GPS/Maps for Positioning

DSRC for Awareness

Network for Cybersecurity

AI for Decision-Making

On-Board Data Collection

Radar/Camera for Crash Avoidance

Driver Information Systems

Reliability

Security

HMI

Automation Challenges Include:



- **Human Factors (Driver Engagement/Re-engagement)**
- **Sensor Performance**
- **Artificial Intelligence Decision-Making Capability**
- **Electronic Control Systems Safety**
- **Cybersecurity**
- **Testing and Evaluation Methodology**
- **Regulatory Approaches:**
 - Performance requirements/objective testing for various levels of automation.
 - Standardization - Are different concepts for achieving automation compatible on the roadway?
- **Operating environment - operating in mixed traffic and on public roads?**
- **Infrastructure modifications**
- **Liability**
- **etc.....**

Motor Vehicle Automation Research Roadmap

Goal: to improve motor vehicle safety by investigating the requirements for automated driving that is:

- **Operational only to the extent granted by the driver**
 - Including override capability
- **Electronically Reliable and Secure**
 - Functionally safe w/appropriate data storage/diagnostics/prognostics
 - Secure from malicious external control and tampering
- **Operationally intuitive for drivers**
 - under diverse driving conditions
 - within limits understood by the driver
- **Focused on reducing crashes!**

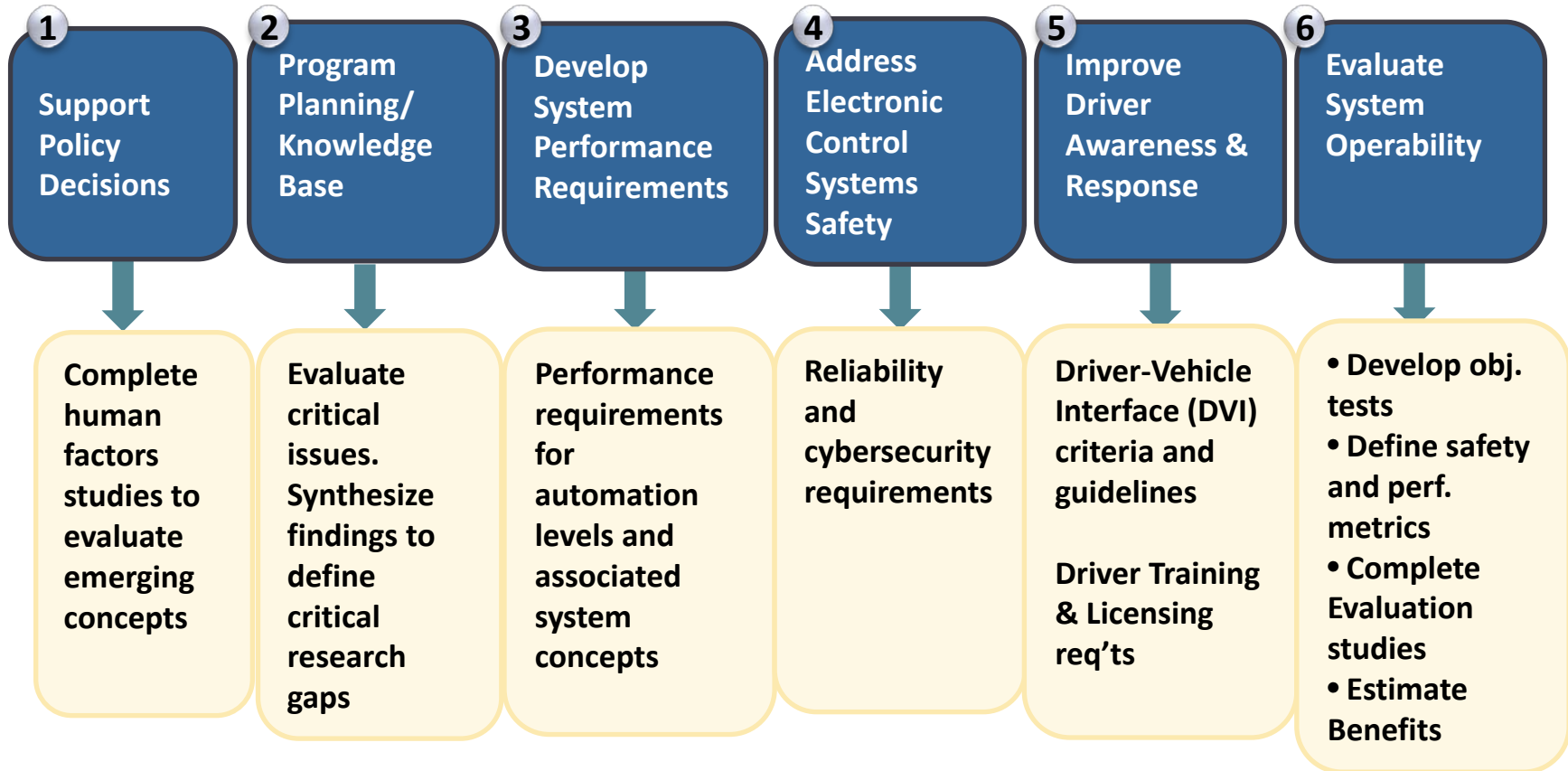
Motor Vehicle Automation Research Roadmap

Objectives

- 1. Support policy decisions on emerging system concepts (Level 2 and Level 3 systems)**
 - Near production concepts are already here
- 2. Facilitate development/deployment of safety enhancing automated systems**
 - Defining concepts of automated operation including the integration of safety systems [safety enhancing concepts]
 - Developing technical requirements and associated performance tests
 - Assess safety benefits & system performance

Motor Vehicle Automation Research Roadmap

Efforts



Outcomes

Automation Challenges Can be Met



- **The goal is a worthy one**
- **Great potential for improving vehicle safety**
 - And other transportation goals
- **NHTSA establishing a comprehensive research plan**
- **Will require collaboration**
 - product developers,
 - insurers,
 - academia,
 - state and federal governments,
 - and many others.....

THANK YOU!



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