
Field Operational Tests of Vehicle Assist and Automation Technologies

California-Oregon VAA Team

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FTA and RITA JPO Vehicle Assist and Automation Demonstration Program

- ✓ Addresses deployment issues
- ✓ Assesses benefits and costs through revenue-service operations

California-Oregon

- BRT and HOV applications
- Lane guidance and precision docking
- Magnetic and GPS technologies

Minnesota

- Bus on highway shoulder application
- Steering assist
- DGPS technology

San Diego

- Bus on highway medians
- Lane guidance and collision warning
Vision technology

Why VAA for BRT?

❑ Problems and Challenges

- Right-of-way purchase costs are high and increasing
- Transit agencies seek safe and cost-effective transit systems
- Transit customers demand high-quality transit service

❑ Potential Benefits

- Reduced right-of-way requirements and infrastructure costs (potential go-no-go decision)
- Reduced accidents
- Reduced operating and maintenance costs
- Smoother ride and level boarding for faster travel and reduced dwell time
- “Rail-like” status
 - ❑ More attractive to choice riders
 - ❑ Encourage transit oriented development



Review of Previous Work

- **R&D on AHS**
- **Lane Assist Systems for Bus Rapid Transit: Needs and Requirements**
- **Lane Assist Systems for Bus Rapid Transit: Technical Scan Tour to Europe**
- **Lane Assist Systems for Bus Rapid Transit: Interface Requirements**



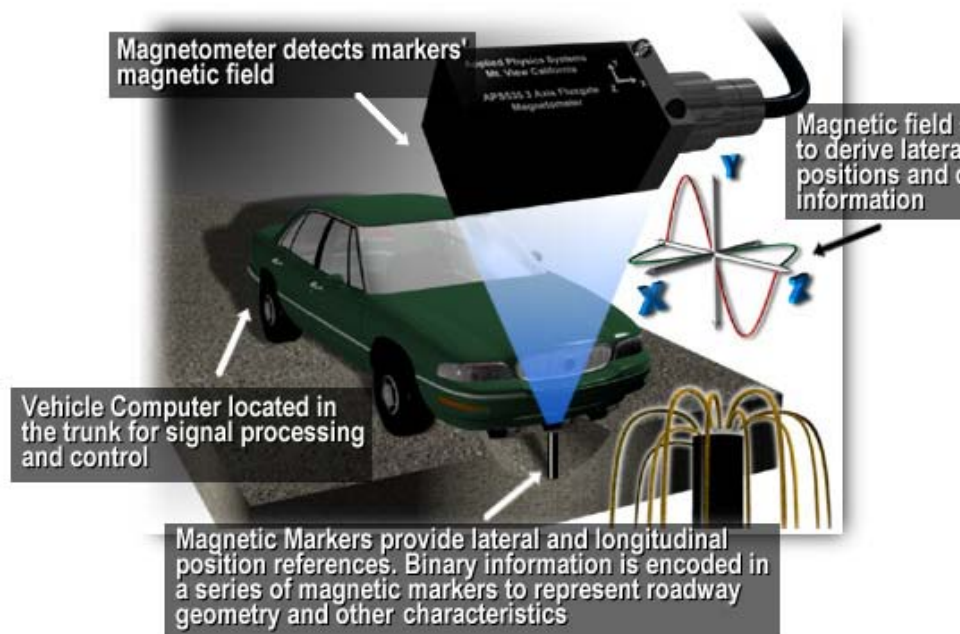
Review of Previous Work (Con'd)

- **Automated Bus demonstration in 2003**
 - To capture imagination of stakeholders and the public at large, and to energize public and private decision makers toward VAA
 - Three-bus platoon with fully automated functions
- **Demonstration of Lane Assist and Precision Docking Systems at ITS World Congress 2005 in San Francisco**

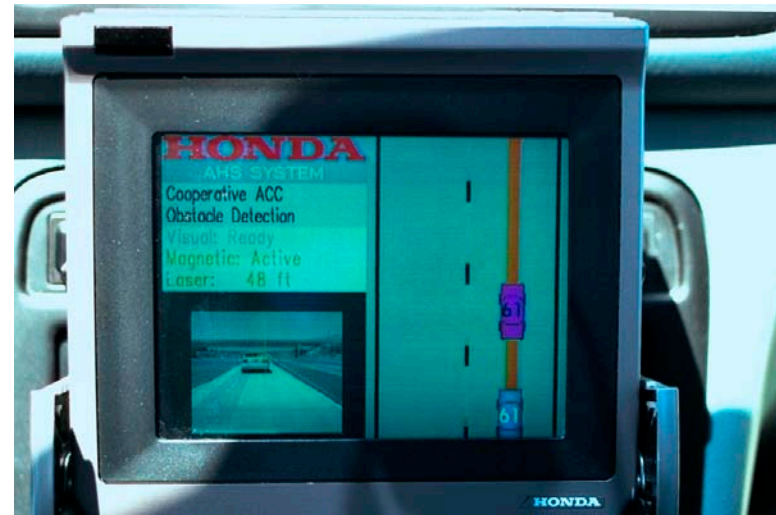


Magnetic Marker System

- Subject to interference
 - Missing magnets (detectable)
 - Unwanted magnets (detectable)
- Not compatible with crashed asphalt
- Require infrastructure installation with \$10-25k per lane mile
- No maintenance



PATH Development: Vision-based Guidance Technology



PATH DGPS/INS/Magnet System



Technology Selection

❑ Criteria

- **Operating conditions**
 - Weather
 - road surface conditions
- **Safety and reliability requirements**
 - Reliability
 - Fail-Safe (sensing) vs. Fail-Soft (system)
- **Performance requirements**
 - Tracking and docking accuracy
 - Robustness
- **Maintenance requirements**
- **Life cycle costs**

❑ Selection:

- **Magnetic marker reference/sensing as primary sensing technology (for both AC Transit and LTD applications)**
- **Combined with GPS to demonstrate fused sensing technologies (AC Transit application)**

VAA Project Background

- Participants
 - FTA, Caltrans, Transit operators (AC Transit & Lane Transit District), UCB/PATH, Industrial subcontractors
- Two guidance technologies:
 - Magnetic sensing
 - DGPS based

Revenue Service (Deployment) →→

- Product Development (Robustness/Reliability)
- Safety: Redundancy Operations (HW/SW)
- Safety: Fault Detection/Operations–All aspects
- Customer Satisfaction (agencies, operators, passengers, contracts, ...)
- Re-design for deployment in almost every aspect
- Very little margin for mistakes

- Project goals
 - Demonstrate the technical merits and feasibility of VAA technology applications
 - Access benefits and costs
- Project durations
 - Component development, system integration and refinement primarily in the first two and half years
 - Revenue operation starts 2012

VAA Project Scope

- **LTD, Eugene Oregon**
 - 2.5 miles of single/double dedicated ROW
 - One 60ft New Flyer BRT bus
 - Functions to be tested:
 - Lane guidance for on dedicated BRT lane
 - Precision docking
- **AC Transit**
 - A 3 mile section of HOV lane, on the California Highway 92 freeway from Hesperian Blvd. to the San Mateo Bridge toll plaza
 - Two MCI (50ft) coaches
 - Functions to be tested:
 - Lane guidance on HOV lane
 - Guidance through toll bridge
- **Full range of VAA applications for BRT**
 - Highway and urban BRT applications
 - Precision docking and guidance
 - Very low to highway speed (65 mph)
 - Degrees of driver assist

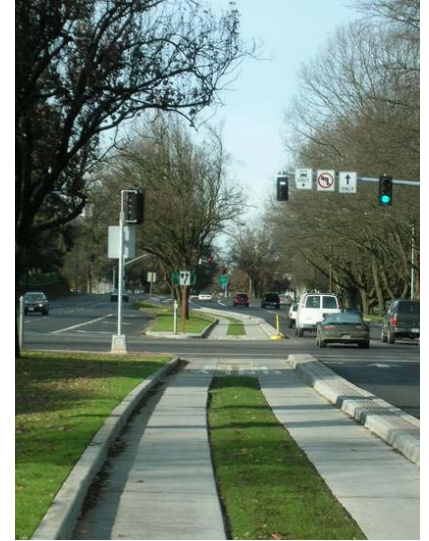


VAA FOT in Revenue Service

-- Design & Development for Deployment

- Revenue service elevates design requirements of automated control
 - Apply product development methodologies (reliability + maintainability)
 - Prefer to use embedded controllers and sensors
 - Emphasize on safety design (redundancy + fault detection/management)
 - Fail-safe and fail-soft
- Deployment requires professional installation
 - Installation not to degrade bus normal operations
 - Normal maintenance to be straightforward (visual inspection, fault reporting, data collection)
 - Most repairs could be conducted by transit personnel (spare part replacement)
- Deployment requires the handling of all operational modes
 - Work in all possible operational conditions and scenarios (different drivers, speeds, weather, traffic conditions, transition methods, ...)
 - Detect and manage all (known) faults
- Revenue service demands addressing any (new) issues
 - Work through operational and other issues (e.g., policy, legal, institutional) with transit agencies

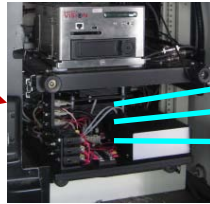
VAA Test (Oregon): Lane Transit District Precision Docking + Lane Guidance



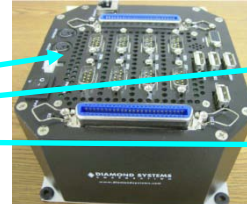
LTD Automated Bus (New Flyer, 60')

VAA System Installation/Configuration

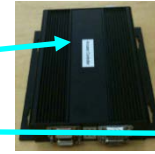
J1939 connection



Instrument Cabinet



Control computer (2)



Actuator controller



HMI controller (2)

Buzzer (2)



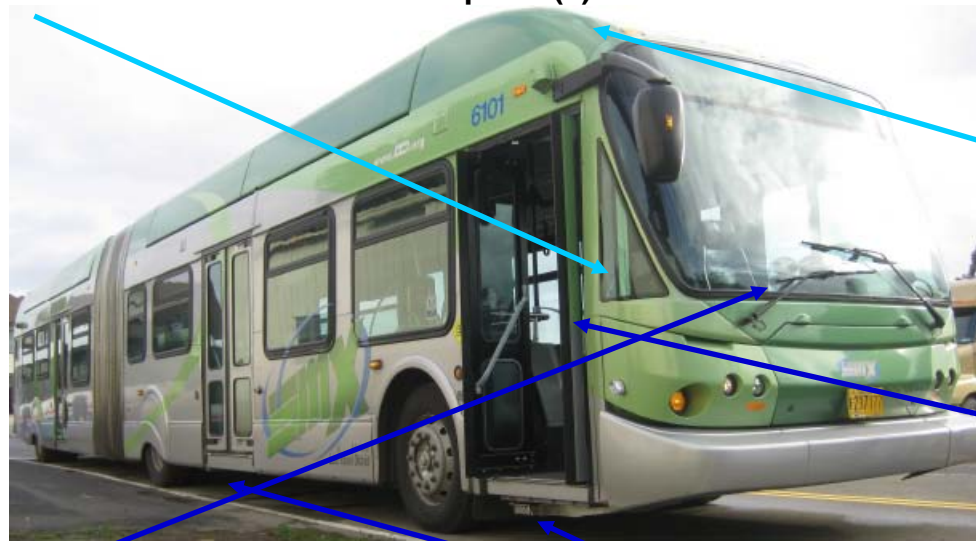
Indicators (2 sets)



Switch & button



Steering actuator



GPS



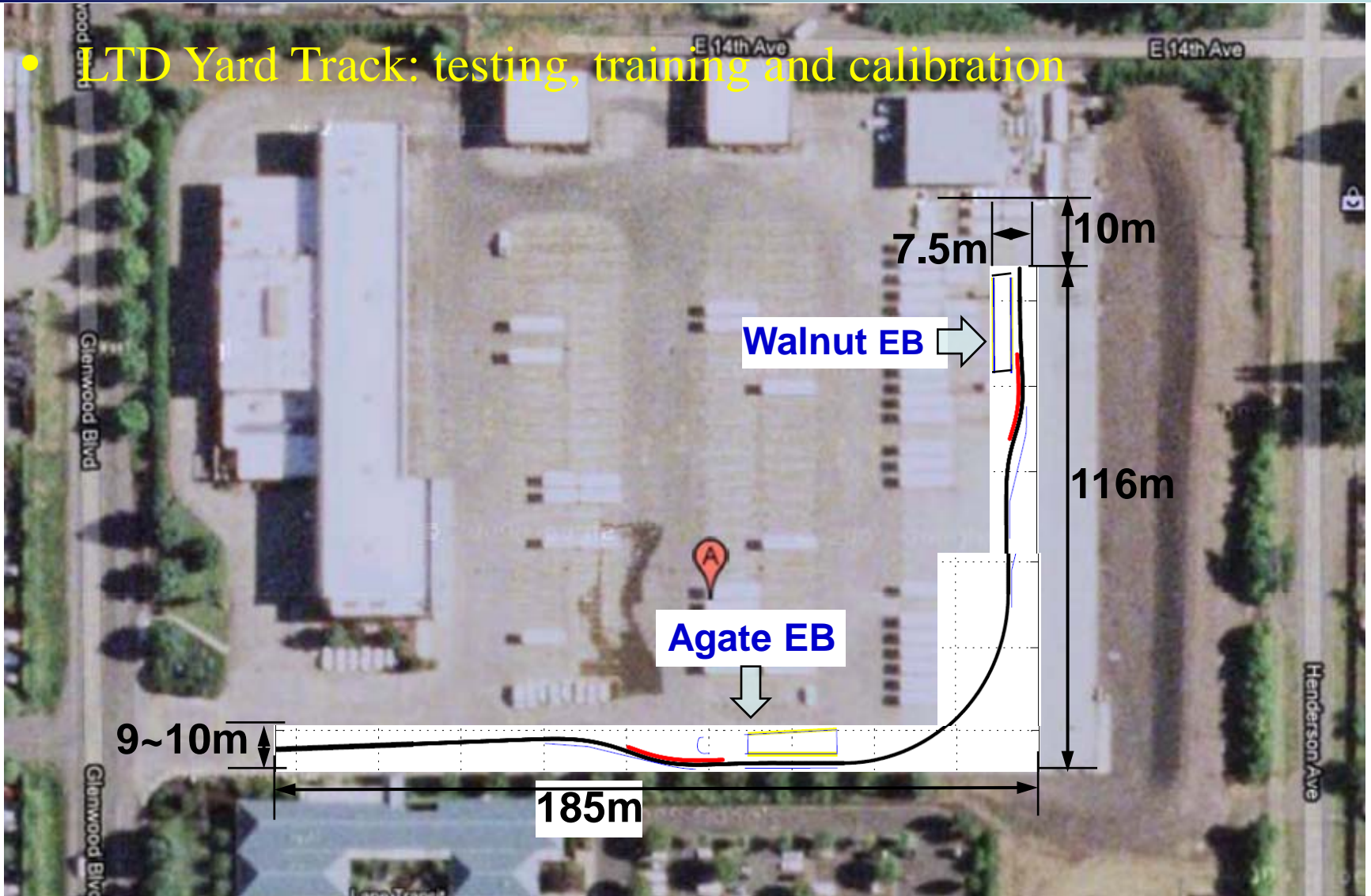
Yaw rate gyro



Front & rear magnetometer sensor bars (2)

LTD Automated Bus Yard Track Results: LTD First Test Drives

- LTD Yard Track: testing, training and calibration



LTD Automated Bus Preliminary Results: Docking Performance on Replicated Stations



Testing on BRT Corridor



Summary

- The VAA FOT addresses deployment issues and benefits/costs through revenue-service operation
- California-Oregon team selected magnetic guidance as the primary guidance technology based on thorough evaluation and technical merits
- Full range of VAA applications for BRT is to be field tested
 - **Highway and urban BRT application**
 - **Precision docking and guidance**
 - **Very low to highway speeds (65 mph)**
- FOT will begin in the fall/winter of 2012

Questions

- Please contact Wei-Bin Zhang
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