



COMPARISON OF PIANC, ANKUDINOV and CADET SHIP SQUAT PREDICTIONS

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- **Introduction**
 - Squat major component of underkeel clearance (UKC)
 - Consists of underway sinkage (vertical motion of hull) and dynamic trim (rotation about center of rotation)
 - Increased interest in ship squat in deep-draft navigation community
 - Compare CADET predictions with Ankudinov & PIANC squat formulas
- **PIANC Squat Formulas**
 - Barrass
 - Eryuzlu et al
 - Huuska/Guliev
 - Römisch
 - Yoshimura
- **Ankudinov Squat Formula**
- **CADET/BNT Squat Program**
- **Ship and Channel Parameters**
 - Port of Savannah, Georgia
 - Susan Maersk Containership
- **Comparisons**
 - Unrestricted Channel (U)
 - Light and Fully-loaded
 - 3 Water Depths
- **Summary and Conclusions**



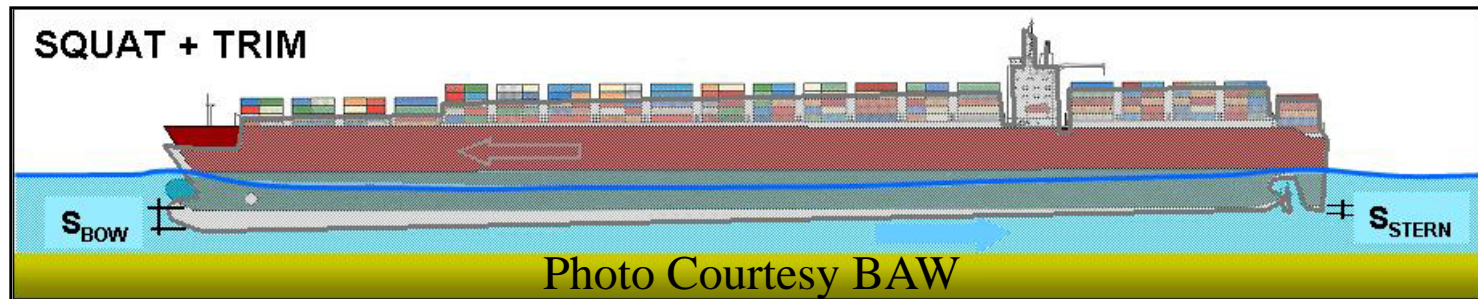
Introduction

- **PIANC ship squat formulas**
 - Empirical
 - Limited lab and field measurements
 - Developed for past generation ships
 - User friendly, but limited ship and channel parameters
 - 3 idealized channel cross-sections
 - Widely used and accepted
 - No one formula best for all scenarios
- **Ankudinov ship squat formula**
 - Recent revisions
 - Thorough and complicated
 - Ship & channel parameters
 - Mid-point sinkage & trim
- **CADET program**
 - Risk-based tool for predicting underkeel clearance (UKC)
 - Based on Navy's tools for deep draft ships in shallow channels
- **CADET squat module**
 - Beck Newman Tuck (BNT)
 - Based on Beck Newman Tuck (BNT) slender body theory
 - Numerical modeling ship lines with potential flow theory
 - Validated with model tests



PIANC Squat Formulas I

- Five of most user friendly and “popular”
 - Barrass
 - Eryuzlu et al
 - Huuska/Guliev
 - Römisch
 - Yoshimura
- All give bow squat
- Stern squat
 - Only Römisch predicts stern squat for all channels
 - Barrass stern only for unrestricted or open channels and other channels depending on C_B value





PIANC Squat Formulas II

- **Barrass**

$$\frac{KC_B V_k^2}{100} = \begin{cases} S_b & C_B > 0.7 \\ S_s & C_B \leq 0.7 \end{cases}$$

- **Eryuzlu et al.**

$$S_b = 0.298 \frac{h^2}{T} \left(\frac{V_s}{\sqrt{gT}} \right)^{2.289} \left(\frac{h}{T} \right)^{-2.972} K_b$$

- **Huuska/Guliev**

$$S_b = C_s \frac{\nabla}{L_{pp}^2} \frac{F_{nh}^2}{\sqrt{1 - F_{nh}^2}} K_s$$

- **Römisch**

$$S_b, S_s = C_V C_F K_{\Delta T} T$$

- **Yoshimura**

$$S_b = \left[\left(0.7 + \frac{1.5T}{h} \right) \left(\frac{BC_B}{L_{pp}} \right) + \frac{15T}{h} \left(\frac{BC_B}{L_{pp}} \right)^3 \right] \frac{V_e^2}{g}$$



Ankudinov Squat I

- **Mid-ship sinkage S_m**
 - Ship propeller
 - Ship hull
 - Ship speed
 - Water depth
 - Channel
- **Trim T_r**
 - Ship propeller
 - Ship hull
 - Ship speed
 - Initial trim
 - Bulbous bow
 - Stern transom





- **Maximum squat S_{Max}**

$$S_{Max} = L_{pp} (S_m \mp 0.5 T_r)$$

- **Mid-point sinkage S_m**

$$S_m = \left(1 + K_P^S\right) P_{Hu} P_{F_{nh}} P_{+h/T} P_{Ch1}$$

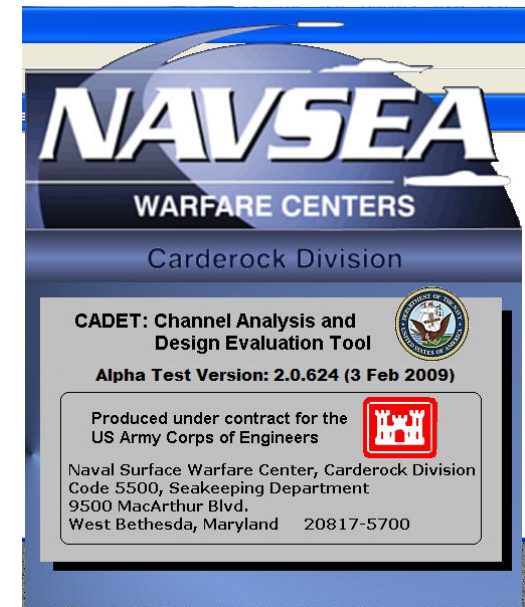
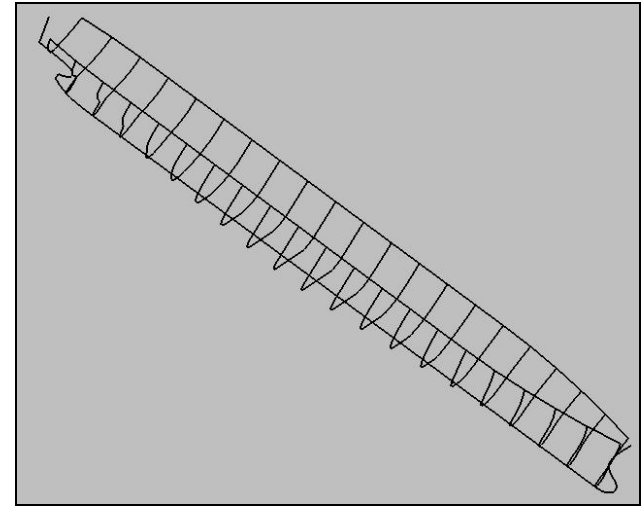
- **Trim T_r**

$$T_r = -1.7 P_{Hu} P_{F_{nh}} P_{h/T} K_{Tr} P_{Ch2}$$



CADET Organization

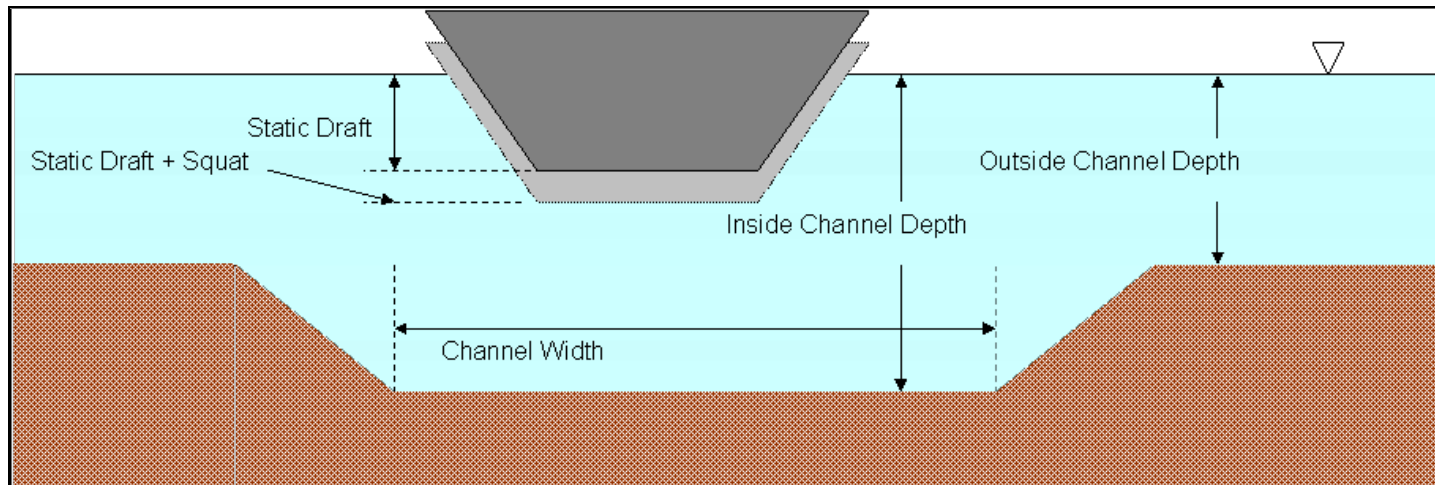
- **Ship**
 - Hull geometry and ship lines
 - Static draft and trim
 - Loading
 - Ship speeds
 - Control points
 - BNT ship squat
 - Heave, pitch and roll transfer functions
- **Project**
 - Channel reaches
 - Directional spectral waves and probabilities
 - Corresponding ships, BNT squat predictions, and loading conditions
- **Analysis**
- **Results**





BNT Ship Squat Predictions

- **Based on early work of Tuck (1966 and 1967)**
- **Beck and Newman expanded to include typical dredged channel (1975)**
- **Sinkage and trim from dynamic pressure on hull**
- **Sorted by depth Froude Number and converted to squat**





Savannah Entrance Channel, Georgia

- **14 nm Outer Channel**
 - Subject to waves
 - Existing depth of 44 ft MLLW
 - Plans to dredge to 50 ft
 - Tide range 8 ft
 - Offshore 5.8 nm segment like Unrestricted or open channel with Width = 600 ft





Susan Maersk Containership

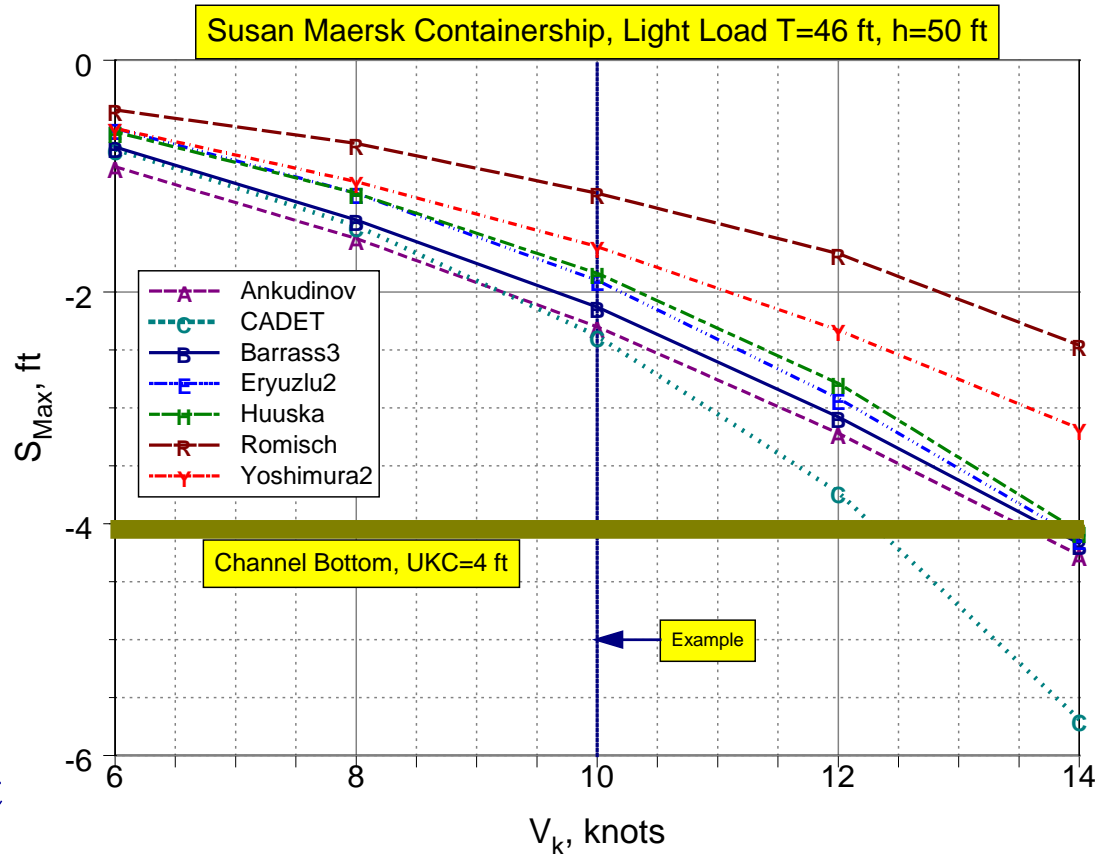


- $L_{pp} = 1,088$ ft
- $B = 140.4$ ft
- **Draft**
 - Light load $T = 46$ ft
 - Full load $T = 47.5$ ft
- $C_B = 0.65$
- $V_K = 8$ to 14 kts



Light Load $T=46$ ft, $h=50$ ft ($h/T=1.09$)

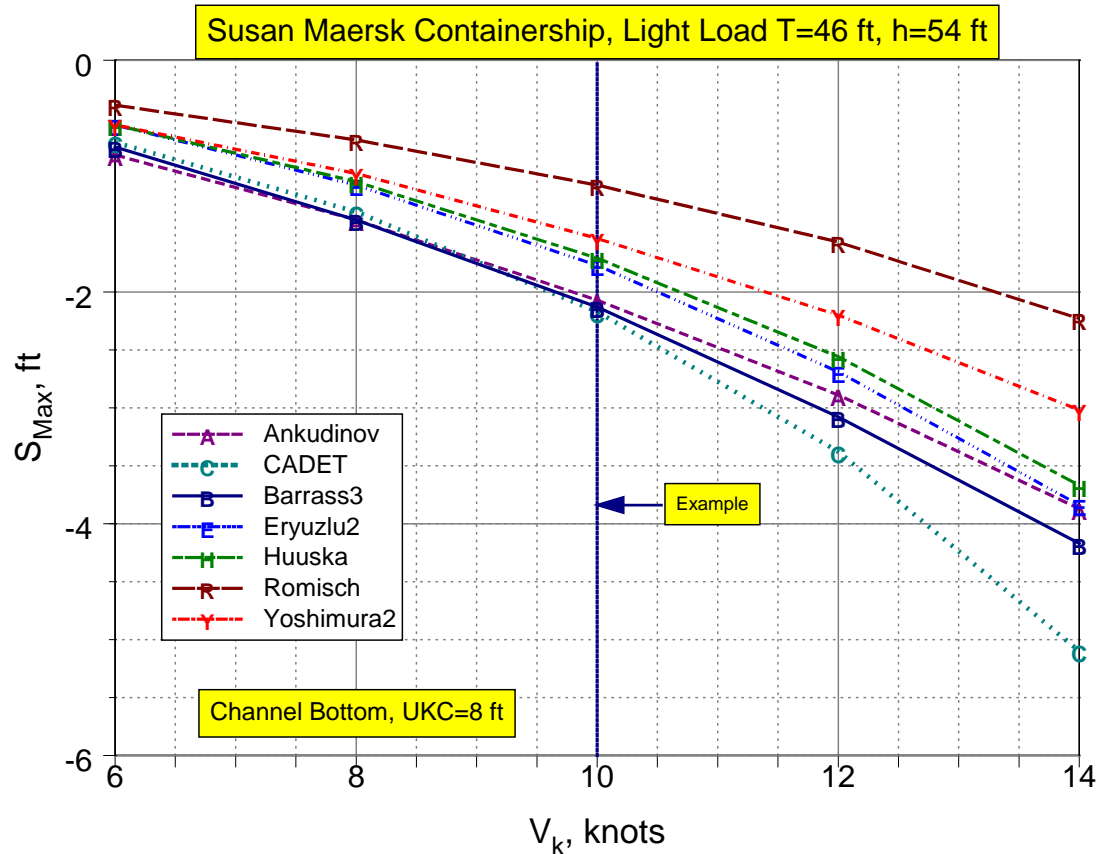
- No tide
- Available UKC=4 ft
- Ankudinov & CADET general agreement with PIANC predictions
- Both conservative
- Ankudinov tracks OK
- CADET tracks OK to $V_k=10$ kt
- Example @ $V_k=10$ kt
 - PIANC Ave=1.7 ft
 - Ankudinov=2.3 ft
 - CADET=2.4 ft
- Grounding due to squat at $V_k=12+$ kt





Light Load $T=46$ ft, $h=54$ ft ($h/T=1.17$)

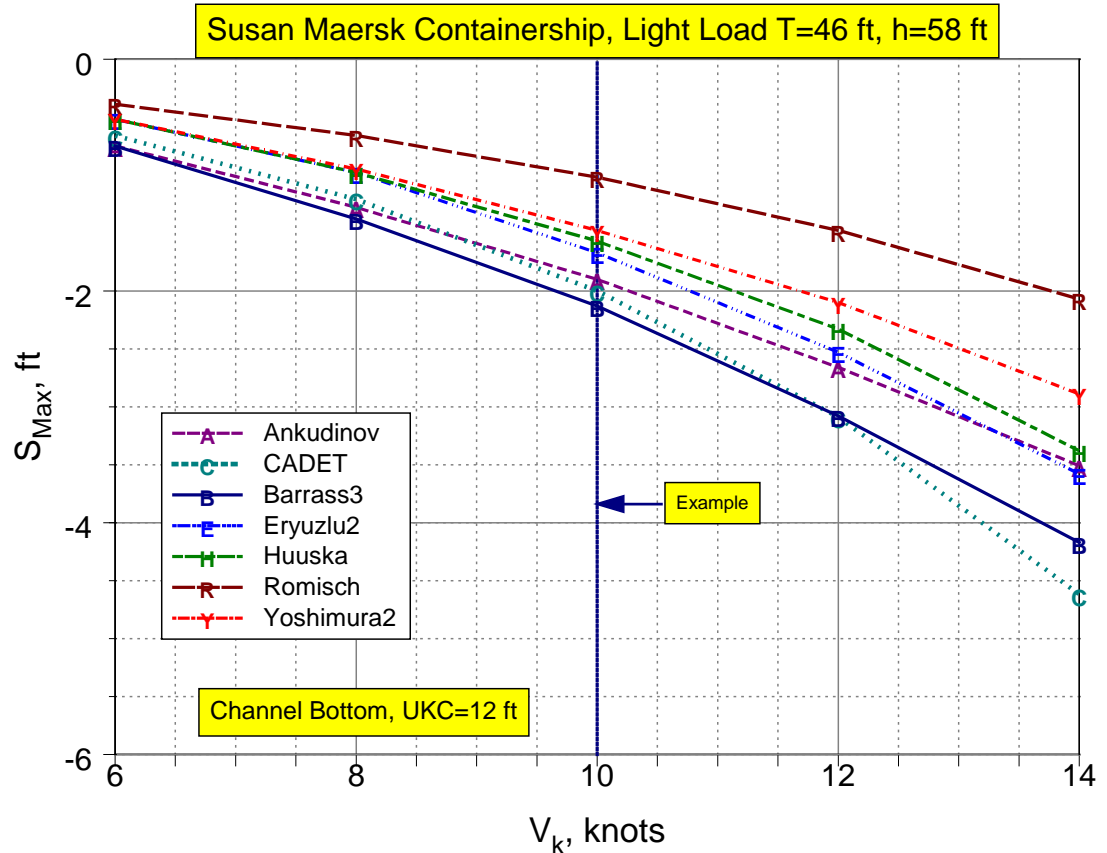
- Tide=4 ft, 4 hr/day, 365 days/yr
- Available UKC=8 ft
- Ankudinov & CADET general agreement with PIANC predictions
- Both conservative
- Ankudinov tracks OK
- CADET tracks OK to $V_k=12$ kt
- Example @ $V_k=10$ kt
 - PIANC Ave=1.6 ft
 - Ankudinov=2.1 ft
 - CADET=2.2 ft
- No grounding due to squat





Light Load $T=46$ ft, $h=58$ ft ($h/T=1.26$)

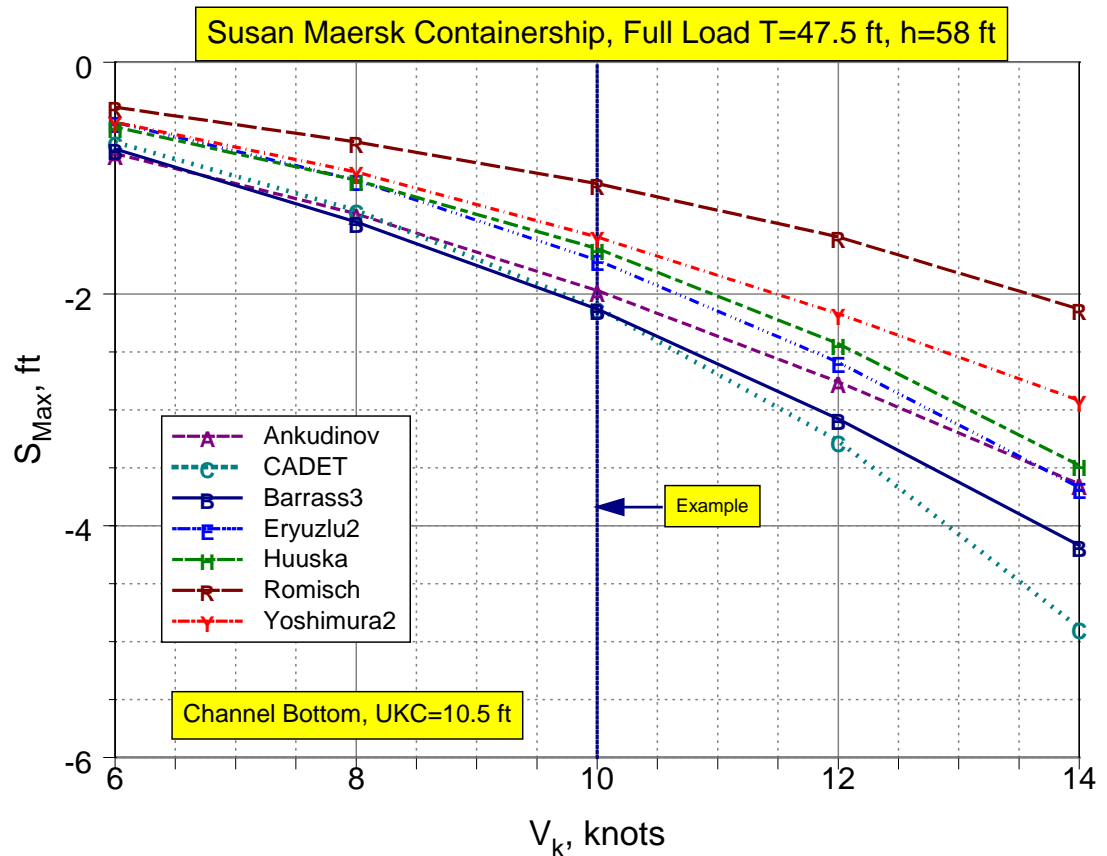
- Tide=8 ft, 1 hr/day, 7 days/yr
- Available UKC=12 ft
- Ankudinov & CADET general agreement with PIANC predictions
- Both conservative
- Ankudinov tracks OK
- CADET tracks OK to $V_k=12+$ kt
- Example @ $V_k=10$ kt
 - PIANC Ave=1.6 ft
 - Ankudinov=1.9 ft
 - CADET=2.0 ft
- No grounding due to squat





Full Load $T=47.5$ ft, $h=58$ ft ($h/T=1.22$)

- Tide=8 ft, 1 hr/day, 7 days/yr
- Available UKC=10.5 ft
- Ankudinov & CADET general agreement with PIANC predictions
- Both conservative
- Ankudinov tracks OK
- CADET tracks OK to $V_k=12+$ kt
- Example @ $V_k=10$ kt
 - PIANC Ave=1.6 ft
 - Ankudinov=2.0 ft
 - CADET=2.1 ft
- No grounding due to squat





Summary and Conclusions

- **Comparisons of numerical CADET with PIANC and Ankudinov empirical squat prediction formulas**
- **Theory, advantages, and disadvantages of PIANC, Ankudinov, and CADET squat predictions presented and discussed**
- **Susan Maersk containership, 3 water depths, 5 ship speeds for unrestricted or open channel type**
- **CADET and Ankudinov reasonable agreement with PIANC predictions, conservative side**
- **Ankudinov and CADET squat predictions can be used with confidence in deep-draft channel design**



Questions?





Recent Interest in Ship Squat

- **Capt Stephen Best, Port of Vancouver, Canada**
- **Capt Richard A. Hurt, Port of San Francisco, CA**
- **Albert Lavanne, Engineer, Port of Rouen Authority, France**
- **Karin Hellström, 2nd Officer, M/T Prospero, Donsotank, Sweden**
- **Papoulidis Panagiotis, Master Mariner, Greece**
- **Capt. Marco Rigo, Venice, Italy**
- **Capt. Michael Lloyd, Senior Advisor, Witherby Seamanship International Ltd, United Kingdom**
- **Anton Holtzhausen, Cape Town, South Africa**
- **Capt Jonathon Pearce, Marico, United Kingdom**
- **Nisrine Alderf, PhD. Student, UTC University of Technology of Compiègne, France**



Challenge Questions

- **Near term and long term visions for MTS**
- **Drivers shaping MTS**
 - Size of ships
 - Safety
- **Near term and long term research required**
 - Ship squat for larger ships
 - Vertical and horizontal ship motion prediction
 - Ship interaction with entrance channels, non-symmetrical channels, other ships during passing and overtaking
- **Advantages of national CMTS R&D strategy**
 - Consistent and proven design and guidance
 - Improved safety
- **Challenges of national CMTS R&D strategy**
 - Consensus among various parties
 - Research funding