Field Measurement of Delay at Signalized Intersections

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For the past five years, studies of delays at signalized intersections have been in progress at the Institute of Transportation and Traffic Engineering, University of California. These studies have dealt with methods for field measurement of intersection delay, and with the effects of different signal timing plans on stopped-time delay during daylight hours at signalized intersections in the San Francisco Bay Area.

Three methods for measuring stopped-time delay were compared: (1) The ITTE delay meter, which accumulates vehicle-seconds of stopped time; (2) a sampling method for estimating vehicle-seconds of stopped time; and (3) use of spaced serial photos to obtain both stopped time and travel time for each vehicle. All three methods were found to be satisfactory for obtaining stopped-time delay at signalized intersections. The spaced serial photo method requires more manpower for reduction of data, but is the only one of the above methods suited for studying travel-time delay at signalized intersections.

A second phase of the study dealt with a comparison of stopped-time delay at threephase signalized intersections with traffic-actuated vs. fixed-time control. As was expected, the actuated timing was better able to accept short-term fluctuations than fixed-time signals. At intersections with pedestrian movements, the use of pedestrian timers permitted timing plans which substantially reduced vehicular delay, especially in off-peak hours. The use of an overlap sequence in the timing of three-phase signals with heavy left-turn movements from one direction only can materially reduce delay in both peak and off-peak hours.

A third phase of the study dealt with "unnecessary" delay, defined as that portion of stopped-time delay which occurs while no traffic is using the intersecting street. The percent of delay classed as "unnecessary" was substantially lower with actuated as compared with fixed-time control, for tests made in off-peak hours at several intersections.

Stopped-time delay also was compared for semi-actuated and full-actuated traffic signal controls at two urban intersections. Stopped-time delays were substantially lower for full-actuated control, as compared with semi-actuated control, for the signal timings studied.

Stopped-time delay also was studied at two signalized intersections 1,185 feet apart to ascertain the effect on delay of coordinating the timing of two fixed-time signals. With the coordinated signal timing plan, the delay to the main street traffic in both peak and off-peak hours was less than half the delay experienced when using actuate traffic signal control without coordination of the timing of the two signals.

Due to the many variables and to fluctuations in traffic and parking conditions, it is a time-consuming job to isolate, in field studies, the effect on delay of each change in condition at an intersection. More study is needed of optimum timing of signals, the placement of detectors, and the effects on delay of coordination of timing of traffic-actuated signals. It thus is not possible to draw general conclusions at this time about the effects on delay of signal timing variations, placement of detectors, turning movements, or volume at all levels up to the possible capacity of an intersection.

• STUDIES of vehicular delay at signalized intersections have been carried on at the University of California for the past five years. The purposes of these studies have been (1) to investigate methods for measuring delay, and (2) to compare the delay which resulted when different types of traffic signal controllers were used at the same intersections. Such data should be useful as a guide in selection of the most efficient type of controller for intersections having comparable conditions.

Before discussing the delay studies, however, it should be pointed out that delay is only one of several factors to be considered in evaluating the efficiency or effectiveness of traffic controls at an intersection. Other factors include the following:

1. Motorists' desires—motorists may prefer one type of control even though the average delay per vehicle is greater. For example, they may prefer the certainty of right of way provided by a signal even though delay at some intersections is lower when stop signs are used (1).

2. Use of traffic actuated equipment seems to have a psychological advantage since many motorists feel that they have a part in causing the signal to change to green.

3. Comparative accident experience also is a factor in selecting type of intersection control.

4. Other factors include costs of equipment and its maintenance, and comparative costs of vehicle operation.

TYPES OF DELAY

Delays to vehicles in traversing intersections have been subdivided into the following types for purposes of this study.

Travel-Time Delay

This type of delay for an individual vehicle is the difference between the actual time required to traverse some fixed distance at the approach to an intersection, and the travel time which would have been required had the vehicle been able to continue at the average speed of approaching traffic.

Stopped-Time Delay

This is the time an individual vehicle is standing still while waiting in line in the approach to a signalized intersection. Average stopped-time delay is the average of stoppedtime delays for all vehicles approaching during the period of time.

"Unnecessary" Stopped-Time Delay

That portion of the stopped-time delay which occurs when there is no vehicle entering or approaching on the opposing legs of the intersection.

Percent Stopped

The ratio of the number of vehicles which come to a stop in approaching an intersection, to the total number entering in the same period of time, expressed as a percentage.

The average travel-time delay appears to be the type of delay which would have the greatest significance in comparing the effectiveness of different traffic control devices. This type of delay is about the only type which can be used to compare delay under signal vs. stop-sign control (2).

Stopped-time delay, however, is much easier to measure than travel-time delay. Thus, one part of this study investigated the correlation between stopped-time delay and travel-time delay.

METHODS FOR MEASURING DELAY

Three methods for measuring delay at signalized intersections were investigated. These methods, which are explained more completely in an earlier paper (β) , are described briefly below:

The ITTE Delay Meter

This is a delay meter which accumulates vehicle-seconds of stopped time. This device consists of electrically operated counters which add vehicle-seconds of stopped time at rates which are directly proportional to the number of vehicles which are standing at any instant. The meter is operated by keeping a rotary switch or handle adjusted to the position corresponding to the number of cars standing and waiting to resume motion (See Figure 1).

The Sampling Method

A visual sampling method for estimating vehicle-seconds of stopped time. At periodic intervals (such as every 15 seconds), the observer determines the number of cars stopped in the approach to the intersection, and records the number of stopped cars corresponding to the exact time of the observation.

The Spaced Serial Photo Method

A method for obtaining travel time and stopped time for each vehicle, utilizing photographs taken at intervals of $\frac{1}{2}$, 1, or 2 seconds apart. Adaptation of spaced serial photos to studies of intersection delay by the ITTE has been described by Van Til (4). Figure 2 shows the camera, and Figure 3 shows a typical sequence of two pictures, with the identifying picture number.

These three methods for measuring stoppedtime delay were used simultaneously at two intersections in order to permit comparisons of manpower requirements and of accuracy. The data obtained by the camera method also permitted a comparison of travel-time delay with stopped-time delay. Altogether, 21 separate 15-minute periods of data were obtained for this phase of study; detailed results have been reported earlier (3) and are only summarized here.

Figure 4 shows the distribution of travel times for all vehicles while traversing a distance from an advance check point to the stop line at one approach to a three-phase signalized intersection in San Francisco during an afternoon hour. Also shown are the distribution of individual travel times for vehicles which stopped, as obtained with the camera, and the travel times for vehicles which did not stop. A total of 735 vehicles were timed by the camera during this hour, with 38 percent of this number being able to proceed through the intersection without stopping.



Figure 1. ITTE delay meter in operation.

Travel-time delay is obtained by subtracting from each individual travel time, an average travel time corresponding to a "no delay" condition. The travel time corresponding to the sixty-seventh percentile speed of the nonstopping vehicles was taken as the travel time corresponding to the "no delay" condition. When this value is subtracted from each individual travel time, there result the distributions of travel-time delays and stoppedtime delays as shown in Figure 5. Some traveltime delays are shown as negative values, because some vehicles were traveling faster than the speed corresponding to the value picked for the "no delay" condition. The average stopped-time delay for this sample. as shown on this figure, was 14.37 seconds per vehicle. Travel-time delay averaged 18.48 seconds per vehicle.

Table 1 shows a comparison between average travel-time delay and average stoppedtime delay for sixteen 15-minute periods of data, as taken at the two approaches studied. Column 6 has percentage figures which show average stopped-time delay as percentages of average travel-time delay. The percentages at the San Jose Avenue approach are above



Figure 2. Camera used in delay studies.



Figure 3. Numbered spaced serial photos taken for delay studies at San Jose Avenue.

70 percent in every case. Average stoppedtime delay at the approach on Eastshore Highway (in a suburban area), was about 55 percent of average travel-time delay during non-peak hours. This percentage figure averaged 66 percent during peak-hour conditions.

Results at these two intersections indicate that, for the conditions of approach speeds and signal timing, the measurements of stopped-time delay provide a method for evaluating a substantial portion of the total delay. The portion of the total delay which is evaluated by stopped-time measurements may also be considered to reflect the variable portion which is related to changes in the timing of the signals.

The average stopped-time delay per vehicle, as obtained by each of the three methods, is compared in Tables 2, 3 and 4, for each of the twenty-one 15-minute periods of study. The tables show the percentages by which the results obtained with the delay-meter and the sampling method differed from the results obtained with spaced serial photos.

The delay-meter method yielded average stopped-time delays for individual 15-minute periods which varied from 13.3 percent higher than the camera method to 22.9 percent less. When three or more 15-minute periods were grouped, the results did not deviate more than 9 percent from those obtained with the camera.

The visual sampling method consistently yielded results which, when grouped for similar volumes, were all within 6.4 percent of the values obtained by the camera method at these two intersection approaches.

These data indicate that both the delay-



Figure 4. Distribution of vehicle travel times on San Jose Avenue, off-peak hour, November 20, 1953.



Figure 5. Travel-time delay vs. stopped-time delay. San Jose Avenue, off-peak hours, November 20, 1953.

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LAY FROM (CAMERA	STUDY	AT TV	VO INT	ERSEC-
(1)	(2)	(3)	(4)	(5)	(6)
Time	Volume Vehicles Per Hour	Percent Stopped	Average Travel- Time Delay	Average Stopped Time Delay	Average Stopped Delay as Percent of (4)
E	astshore H	ighway,	Oct. 16,	1953	
p.m.	1	Į	seconds	seconds	
2:00-2:15	152	26.3	10.2	5.5	53.9
2:15-2:30	162	22.8	7.8	4.3	55.1
2:45-3:00	173	39.3	11.4	6.4	56.1
4:30-4:45	335	42.4	14.4	9.2	63.9
4:45-5:00	347	39.2	16.2	8.7	53.7
5:00-5:15	340	42.1	17.2	12.2	70.9
5:15-5:30	329	57.1	22.7	17.2	75.8
	San Jose A	Ave., No	v. 20, 19	53	
2.15-2.30	172	56 4	17.7	13.8	78.0
2:30-2:45	199	64.3	17.7	13.3	75.1
2:45-3:00	183	61.7	18.5	14.6	78.9
3:00-3:15	181	64.1	20.0	15.9	79.5
3:30-3:45	223	59.6	17.5	14.2	81.1
3:45-4:00	248	64.1	20.1	15.2	75.6
4:15-4:30	297	66.3	21.1	16.7	79.1
4:30-4:45	450	80.9	29.2	22.6	77.4
4;45-5;00	461	59.4	21.5	16.3	75.8

		TABLE	1		
STOPPED-T	IME DE	LAY VS	TRAVEL	TIME	DE-
LAI FROM	CAMERA	a si udi	AF FWU	INTER	SEC-
		TIONE			

MPAR	ISON	OF	AJ
Y BY	THR	ĔĒ	ΜI

TABLE 3 VERAGE STOPPED-TIME DE-ETHODS AT SAN JOSE AVE.. NOV. 20, 1953

	Camera Method:	Percent of Differences from Camera Method			
Time	Average Stopped- Time Delay	By delay meter	By sampling method		
<i>p.m.</i>	sec per vehicle	%	%		
2:15-2:30 2:30-2:45 2:45-3:00 3:00-3:15	$13.8 \\ 13.3 \\ 14.6 \\ 15.9$	-10.2 -9.1 -7.8 -8.2	$^{+4.8}_{+1.1}_{+0.6}_{-6.7}$		
One-hour total	14.4	-8.9	-0.3		
3:30-3:45 3:45-4:00	14.2 15.2	$-7.5 \\ -5.4$	$^{+3.8}_{-1.8}$		
Half-hour total	14.7	-6.4	+0.7		
4:15-4:30 4:30-4:45	$\begin{smallmatrix}16.7\\22.6\end{smallmatrix}$		$-3.5 \\ -6.3$		
Half-hour total	20.2		-5.4		
4:45-5:00	16.3		-10.9		

TABLE 2 COMPARISON OF AVERAGE STOPPED-TIME DE-LAY BY THREE METHODS AT EASTSHORE HIGH-WAY, OCT., 16, 1953 COMPARISON OF

	Camera Method:	Percent of Differences from Camera Method			
Time	Average Stopped- Time Delay	By delay method	By samp- ling method		
p.m.	sec per vehicle				
2:00-2:15	5.5	-12.8	-10.5		
2:15-2:30	4.3	+13.3	+0.1		
2:45-3:00	6.4	+7.3	-7.5		
45-min total	5.4	+2.7	-6.4		
4:30-4:45	9.2	+1.8	-11.6		
4:45-5:00	8.7	-22.9	-30.1		
5:00-5:15	12.2	+0.6	+7.3		
5:15-5:30	17.2	-4.4	+3.9		
One-hour total	11.8	-5.4	-4.7		

meter and the sampling method can be used to give reasonably consistent values of accumulated stopped-time delay under the conditions existing at these high-volume approaches. Frequently, during the peak hour, as many as 50 vehicles were waiting at one time, which required considerable dexterity on the part of the operator of the delay meter.

TABLE 4 COMPARISON OF AVERAGE STOPPED-TIME DE-LAY BY DELAY-METER AND CAMERA METHODS

Location and Date	Time	Camera Method: Average Stopped- Time Delay	Delay Meter Difference from Camera Method
	p.m.	sec per vehicle	percent
Eastshore Highway, 8/6/53	2:30-2:45 3:45-4:00 4:15-4:30	$6.2 \\ 5.3 \\ 9.5$	$^{+8.1}_{+8.3}_{+4.4}$
45-min total San Jose Ave., 9/3/53	2:30-2:45 2:45-3:00	7.2 8.0 7.8	+6.2 +5.3 +5.0
30-min total		7.9	+5.2

The sampling method gave unreliable results at an intersection with two-phase fixedtime signals when the cycle length was a multiple of the sampling frequency, and the length of the red light was relatively short. This pointed out the need for care in selecting the time interval for sampling.

The study also revealed that when the lengths of the cycle did not vary materially, the percent of vehicles stopping may be useful as one measure of delay. However, the vehicleseconds of stopped time per vehicle provides a more realistic measure for all different types of signalized control, since this measure takes into account the length of time the vehicles must wait.

DELAY AT THREE-PHASE SIGNALIZED INTERSECTIONS

The next phase of the study investigated the effects on stopped-time delay of different types of three-phase traffic signal controllers at three intersections in the San Francisco Bay Area. Delay meters were used to obtain stopped-time delay for two of the approaches to each intersection, with the sampling method used for measuring delay in the third approach (δ) .

Three approaches for each intersection (one for each signal phase) were studied simultaneously. In general, the afternoon peak-hour direction was selected, with studies made for both off-peak and peak-hour traffic volume conditions.

Eastshore and Carlson Study

Figure 6 shows the layout of the intersection of Eastshore Highway and Carlson Boulevard in a suburban area in Richmond, California. The movements studies included north-bound traffic on Eastshore, left-turning traffic entering from the south on Eastshore, and westbound traffic on Carlson Boulevard. The traffic volume turning left from the north approach is very light. The peak-hour volumes at this intersection appear to approach the practical capacity, with about 1200 vehicles per hour northbound on Eastshore, 320 vehicles per hour turning left and 380 vehicles per hour westbound on Carlson Boulevard.

The intersection is normally controlled by a three-phase full-actuated traffic signal controller with a pedestrian timer and an overlap phase sequence. When there is no vehicle actuation for the left-turn lane on the north approach, the northbound traffic on Eastshore is permitted to continue while the leftturn traffic from the south moves. Since the left-turn traffic from the north is very light, this overlapping sequence operates very frequently at this intersection, and thus adds to the available green for northbound traffic.

The delay studies were made for three signal timing plans, as follows:

1. Full-actuated three-phase signal timing with the permissive overlap sequence and with dial settings as established by the authority having jurisdiction.

2. A full-actuated three-phase timing without the overlap sequence, but with substantially the same dial settings as above.

3. A fixed-time three-phase timing, with separate dial settings for peak and off-peak hours.

Table 5 shows a comparison of stoppedtime delays for the three approaches under off-peak and peak-hour conditions, for the three types of traffic signal control. The dial settings for the controllers were not necessarily the optimum settings for each type of signal control. The results thus apply only for the timings actually used (5).

It is readily apparent from the table that the delay to northbound traffic for the actuated controller with the overlap sequence was substantially less than for either of the other two timing plans, under both off-peak and peak-hour conditions. During the off-peak hour the delay per vehicle was 44 percent less than with the fixed-time signal; a decrease of 3.3 seconds per vehicle. A difference as large as 1.8 seconds is possible due to chance only 2 times in a 100 with the size of sample used. The difference for the peak-hour condition was also statistically significant.

The average values for the fixed-time controller and for the actuated timing without the overlap sequence did not differ materially. During the peak-hour condition, however, the individual 15-minute average for the fixedtime signal varied much more than did the values for the actuated signal, because of the inability of the fixed-time signal to adjust itself to a temporary overload on one leg of the three-phase movement. The two highest 15minute three-leg peak-hour delay values for the fixed time signal averaged 50.5 seconds per vehicle, as compared with 42.1 seconds for the actuated controller with no overlap sequence.

San Jose, Monterey, and Diamond

Measurements of stopped-time delay were also made at the intersection of San Jose Ave., Monterey Boulevard, and Diamond Street in San Francisco. The three major conflicting movements normally were controlled by a three-phase full-actuated traffic signal, with pedestrian push buttons.

Traffic volumes were heaviest on San Jose Avenue, with the westbound volume increasing in the peak hour from 640 to 2172 vehicles per hour in the three lanes. The volumes on Monterey in the evening peak hour were very little different from in the off-peak hours (220



Figure 6. Layouts of the three-phased signalized intersections.

vs 248); on Diamond the off-peak and peakhour volumes were 184 and 368 vehicles per hour, respectively.

Table 6 shows average stopped-time delays during afternoon off-peak hours (1:45-3:00 p.m.), under three signal timing plans, as follows:

1. Actuated Control, without pedestrian timers. Minimum initial intervals: San Jose, 15 seconds; Monterey, 18 seconds; Diamond, 16 seconds.

2. Actuated Control, with pedestrian timers. Minimum initial intervals for Monterey and for Diamond were cut to 8 seconds.

3. Fixed-Time Control, with 75 or 80-second cycles, and with green intervals adequate for pedestrians to cross.

The table reveals that the delay was the least when the intersection was controlled by the actuated signal with the pedestrian timer and the low minimum initial intervals. The average delay per total vehicle is significantly less than for the fixed time signal. It should be noted that the average length of cycle is lower (52 seconds), with this timing plan than with either of the other two timings. The delay to vehicles on San Jose Avenue was cut approximately a third (15.0 to 10.3 seconds per vehicle) by using pedestrian timers with low minimum initial intervals, as compared with a timing plan having initial intervals long enough for pedestrians to cross.

For peak-hour conditions, similar results were obtained, although there were only three 15-minute samples without the pedestrian timers. Table 7 shows that the average delays for the actuated controller with pedestrian timers were significantly lower than for the fixed-time controllers. It is interesting to note also that the average delays for each street were greater when the percent of green for that street was lower.

Portola, Woodside, and O'Shaughnessy

The third intersection studied in this series was at Portola, Woodside, and O'Shaughnessy in San Francisco. Tables 8 and 9 present data on signal timing for both off-peak and peakhour conditions, and the resulting data on stopped-time delay under two signal timing plans. Traffic volumes on the three-lane Portola approach increased from 650 vehicles per hour in the off-peak hour to 1875 vehicles per hour in the peak-hour; for Woodside, the

TABLE 5 COMPARISON OF AVERAGE STOPPED-TIME DELAY WITH THREE SIGNAL CONTROLLERS At Eastshore and Carlson, Richmond, Fall, 1953

					verage Delay per ehicle—Seconds		
Type of Control and Time Period	Volume, 3 Legs, VPH	Avg. Cycle, Secs.		East	shore	Carl	
			3 legs	North	Left T.	son West	
	Off-p	eak (1:0	0-3:00)				
Actuated With overlap No overlap Fixed time	720 796 768	63 82 84	8.9 13.2 13.2	4.3 7.6 7.6	24.6 34.9 34.1	16.6 21.2 22.5	
	Pea	k (4:30-	5:30)				
Actuated With overlap No overlap Fixed time	1872 1984 1908	103 138 110	$21.2 \\ 32.7 \\ 32.5$	$11.5 \\ 25.3 \\ 22.9$	$43.1 \\ 48.6 \\ 64.9$	36.2 41.9 37.0	
COMPARISON LAY IN OFF- TEREY, A	OF AV PEAK ND DIA 1:45-3:0	TABLE ERAGI HOURS MOND 00 p.m. 1	6 E STO 5 AT 6 9 SAN Fall, 19	PPED SAN J FRAN 53	-TIM OSE, ICISC	E DE MON CO	
True of Signal	Control	Ave	rage De S	lay per econds	Vehic	le	
Type of Signat	Control	Total, 3 legs	San Jose	Me ter	on- rey	Dia- mond	
Actuated No pedestrian With pedestria Fixed time	timer an timer.	$15.1 \\ 13.3 \\ 15.6$	15.0 14.5 16. 10.3 20.3 14. 12.8 21.0 19.			16.6 14.7 19.8	
		A	verage	Signal	Timir	ng	
			Apr	orox. pe	ercent	green	
		sec.	San Jose	Me te	on- rey	Dia- mond	
Actuated No pedestrian With pedestris Fixed time	timer an timer.	65 52 79	35 40 39	322	30 21 25	25 22 23	

comparative figures were 300 and 472 vehicles per hour; for O'Shaughnessy, 132 and 516 vehicles per hour.

As shown in Table 8, the average stoppedtime delay for all traffic entering on the three legs in an off-peak hour was about 30 percent less for the actuated control than for the fixedtime control (10.0 vs 14.5 seconds per vehicle). The delay to the major flow on Portola Avenue was reduced almost 60 percent, with the per-

TABLE 7 COMPARISON OF AVERAGE STOPPED-TIME DE-LAY IN PEAK HOUR AT SAN JOSE, MONTEREY, AND DIAMOND, SAN FRANCISCO 4:30-5:30 p.m. Fall, 1953

	Average Delay Per Vehicle—Seconds				
Fype of Signal Control ctuated No pedestrian timer With pedestrian timer	Total, 3 legs	San Jose	Mon- terey	Dia- mond	
Actuated No pedestrian timer With pedestrian timer. Fixed time	$26.6 \\ 20.7 \\ 24.5$	24.3 16.8 20.7	$31.6 \\ 44.8 \\ 34.8$	37.5 31.3 40.0	
	Average Signal Timing				
	Approx. percen			t green	
	sec.	San Jose	Mon- terey	Dia- mond	
Actuated No pedestrian timer With pedestrian timer. Fixed time	101 90 105	50 54 49	22 16 20	23 22 21	

TABLE 8 COMPARISON OF AVERAGE STOPPED-TIME DE-LAY AT PORTOLA, WOODSIDE, AND O'SHAUGH-NESSY IN OFF-PEAK HOURS 2:00-3:00 p.m. Fall, 1953

Turne of Signal	Average Delay Per Vehicle-Second					
Control	Total, 3 legs	Portola	Woodside	O'Shaugh- nessy		
Actuated Fixed time	10.0 14.5	5.6 12.9	14.7 14.6	21.5 22.4		
		Average Signal Timing				
	Cruela	Approx. percent green				
	sec.	Portola	Portola Woodside			
Actuated Fixed time	51 63	48 34	22 30	14 21		

cent of vehicles being required to stop dropping from 76 percent to 46 percent.

There were fourteen 15-minute samples for the actuated timing, and eight 15-minute samples for fixed-time timing. The variation in results was sufficiently low, so that the differences found are statistically significant, and could not have been due to chance alone.

The data for the peak hour shown in Table 9, reveal no great differences between delay values for fixed-time and actuated controls.

TABLE 9 COMPARISON OF AVERAGE STOPPED-TIME DE-LAY AT PORTOLA, WOODSIDE, AND O'SHAUGH-NESSY, IN PEAK HOUR 4:30-5:30 p.m. Fall, 1953

Type of Signal	Average Delay Per Vehicle—Seconds					
Control	Total, 3 legs	Portola	Woodside	O'Shaugh- nessy		
Actuated Fixed time	20.2 21.8	17.0 15.7	$\begin{array}{c} 26.0\\ 26.2 \end{array}$	28.0 34.5		
		Average Si	gnal Timin	g		
	Curcle	Approx. percent green				
	sec.	Portola	Woodside	O'Shaugh- nessy		
Actuated Fixed time	81 74	47 46	21 26	21 18		

However, the size of the sample was too small to permit any statistical comparison. It is interesting to note, however, that the average length of cycle was approximately the same for the two timing plans during this peak-hour condition. The lower percentage of green time on O'Shaughnessy with the fixed-time control is probably the cause of the increased delay on this approach.

Alemany Boulevard Study

Stopped-time delay was obtained on Alemany Boulevard at Santa Rosa Avenue and at Ocean Avenue in San Francisco during 1951–1952 in order to compare different types of two-phase traffic signal controllers and timing plans. Santa Rosa Avenue and Ocean Avenue are 1185 feet apart, and normally are controlled with full-actuated volume-density traffic-signal controllers without interconnection. Figure 7 shows the spacings of signals along Alemany, and the time-space diagram for the fixed-time system which was installed for one part of the study. Alemany Boulevard is an 80-foot street which at the time of the study carried about 1500-2200 vehicles per hour in the peak hour in the southbound direction, and about 600 vehicles per hour in the northbound direction. Calculating machines and delay meters were used in accumulating vehicle-seconds of stopped time, as described by Edward M. Hall in an earlier report (2).

The dial settings used for timing the traffic-



Figure 7. Time-space diagram for Alemany Boulevard.

actuated signals were suggested by officials of the City of San Francisco and/or by the District Office of the California Division of Highways. No claim is made that the settings actually used provided the optimum timing for the conditions. However, the men who timed the signals were experienced in timing trafficactuated signals. The vehicle detectors on Alemany were located 250 feet from the intersection, and the detectors on the side streets were between 40 and 50 feet from the curb line.

Results of the delay studies made during peak-hour conditions at Santa Rosa Avenue are shown in Table 10. This table shows, for each of six signal timing plans, the stoppedtime delay in seconds per vehicle for each of the two studied approaches, the traffic volumes, and the percent of vehicles which stopped.

The lowest delay for the two legs combined was found when using timing plan No. 6, with a volume-density traffic-actuated controller. Only 18.6 percent of the vehicles moving south on Alemany were required to stop. The delay to cross traffic was higher (20.5 seconds per vehicle, with 81.5 percent stopping) than for other signal timing plans. Timing plan No. 4 (full-traffic-actuated controller) showed delay values which compared favorably with the volume-density controller for this location. Delays with the semi-actuated controller and the fixed-time controller were higher. Traffic approaching the fixed-time signal from the approach studied did not have the benefit of coordinated timing of the signals, since this traffic was approaching the first of the three fixed-time signals, as shown by the time-space diagram in Figure 7.

Results of studies made at the Ocean Avenue intersection, for several ranges of volumes, are shown in Tables 11, 12, 13 and 14. The fixed-time controller at this intersection was coordinated with fixed-time controllers at nearby intersections, as shown in Figure 7, thus providing a simple progressive system for Alemany Boulevard.

The results indicate that, for the conditions studied, the fixed-time progressive timing produced delay values for southbound traffic

TRAFFIC AND OPERATIONS

TABLE 10 STOPPED-TIME DELAY IN PEAK HOUR WITH SIX SIGNAL TIMING PLANS AND NO COORDINATION WITH NEARBY SIGNALS Alemany and Santa Rosa, San Francisco, 1951-1952

4:30-5:30 p.m.

Controller and Timing Plan	Street	Volume in Veh/Hr	Percent Stopped	Delay in Seconds per Total Veh.
1. Fixed-time 65 Sec. cycle with 37 Sec. green on Alemany; 1/22/52	Alemany, S.B. Santa Rosa, F.B. Both loss	2192 125 2317	36.8 54.4	6.0 10.3 6.2
2. Semi-actuated Phase A: 36 sec. min.; Phase B: $15 + 5$; max. 30; $3/21/51$	Alemany, S.B. Santa Rosa, E.B. Both less	1580 166 1746	$46.2 \\ 63.2 \\ 47.8$	7.3 10.8 7.6
3. Semi-actuated Phase A: 49 sec. max.; Phase B: 7 + 4, max. 25; 3/28/51	Alemany, S.B. Santa Rosa, E.B. Both legs	1501 207 1708	25.8 70.5 31.3	4.3 17.7 6.0
4. Full actuated (804) Phase A: 25 + 5; max. 75; Phase B: 10 + 5; max. 30; 4/11/51	Alemany, S.B. Santa Rosa, E.B. Both legs	$1646 \\ 152 \\ 1798$	$26.2 \\ 75.6 \\ 30.4$	$3.1 \\ 16.9 \\ 4.3$
5. Volume density (1022) Timing plan A; 3/7/51	Alemany, S.B. Santa Rosa, E.B. Both legs	$1519 \\ 169 \\ 1688$	44.2	5.5 13.7 6.3
6. Volume density (1022) Timing plan B; 4/4/51	Alemany, S.B. Santa Rosa, E.B. Both legs	1545 157 1702	$18.6 \\ 81.5 \\ 24.4$	$\begin{array}{r} 2.4\\ 20.5\\ 4.1\end{array}$

TABLE 11

STOPPED-TIME DELAY IN PEAK HOUR, COMPARING FIXED-TIME COORDINATED TIMING WITH SEVERAL NON-COORDINATED ACTUATED TIMINGS OF A TWO-PHASE SIGNAL Alemany and Ocean, San Francisco, 1951–1952 4:30–5:30 p.m.

Controller and Timing Plan	Street and Direction of Movement	Volume in Veh/Hr	Percent Stopped	Delay in Seconds per Total Veh.
 Fized-time, coordinated for progressive movement on Alemany sec. cycle with 37 sec. green on Alemany; 1/17/52 	Alemany, S.B. Ocean, F.B.	2164 370	8.0 67.3	1.1
 Semi-actuated Phase A: 40 sec. min.; Phase B: 6 + 4, max. 25; 4/26/51 	Both legs Alemany, S.B. Ocean, E.B. Both legs	2534 1572 384 1956	16.7 39.5 64.6 44.4	3.1 6.9 15.0 8.5
 Semi-actuated Phase A: 60 sec. min.; Phase B: 14 + 5, max. 25; 6/6/51 	Alemany, S.B. Ocean, E.B. Both legs	$1653 \\ 392 \\ 2045$	$32.7 \\ 68.9 \\ 39.6$	4.8 17.7 7.3
4. Semi-actuated Phase A: 50 sec. min.; Phase B: 10 + 5, max. 25; 8/22/51	Alemany, S.B. Ocean, E.B. Both legs	1781 355 2136	$39.7 \\ 87.3 \\ 47.6$	7.6 26.4 10.8
5. Full actuated (804) Phase A: $15 + 5$; max. 70; Phase B: $10 + 5$; max. 45; $5/9/51$ and $9/12/51$	Alemany, S.B. Ocean, E.B. Both legs	$1565 \\ 357 \\ 1922$	$24.0 \\ 59.4 \\ 30.6$	3.7 21.6 7.0
6. Volume density (1022) Timing plan C; 5/16/51 (omitting 5:00-5:15)	Alemany, S.B. Ocean, E.B. Both legs	1438 400 1838	$\begin{array}{c} 22.0\\ 66.2\\ 31.6 \end{array}$	$\begin{array}{c} 3.2\\17.9\\6.4\end{array}$
7. Volume density (1022) Timing plan D; 6/20/51	Alemany, S.B. Ocean, E.B. Both legs	1936 361 2297	$25.9 \\ 75.6 \\ 33.7$	$3.4 \\ 17.5 \\ 5.6$
8. Volume density (1022) Timing plan E; 10/10/51	Alemany, S.B. Ocean, E.B. Both legs	$1670 \\ 342 \\ 2012$	$27.9 \\ 66.7 \\ 34.5$	$3.6 \\ 17.4 \\ 5.9$

BERRY: DELAY AT SIGNALIZED INTERSECTIONS

TABLE 12 STOPPED-TIME DELAY AT INTERMEDIATE VOLUMES, COMPARING FIXED-TIME COORDINATED TIMING WITH NON-COORDINATED ACTUATED TIMING Alemany and Ocean, San Francisco, 1951–1952

3:30-4:30 p.m.

Controller and Timing Plan	Street	Volume in Veh/Hr	Percent Stopped	Delay in Seconds per Total Veh.
1. Fixed-time, coordinated for S.B. on Alemany 65 Sec. cycle with 37 sec. gr. on Alemany; 1/17/52	Alemany, S.B. Ocean, E.B.	757 293	10.2 63.5	0.8
2. Semi-actuated See Table 11; 4/26/51	Alemany, S.B. Ocean, E.B. Both legs	689 308 997	29.0 76.5 43.5	4.2 3.3 22.4 9.2
3. Semi-actuated See Table 11, 8/22/51	Alemany, S.B. Ocean, E.B. Both legs	$745 \\ 269 \\ 1014$	$31.1 \\ 87.7 \\ 46.2$	$3.8 \\ 27.8 \\ 10.2$
4. Full actuated (804) See Table 11; 9/12/51	Alemany, S.B. Ocean, E.B. Both legs	783 278 1061	$26.3 \\ 73.0 \\ 38.5$	$\begin{array}{c} 2.6\\12.6\\5.3\end{array}$
5. Volume density (1022) Timing plan C; 5/16/51	Alemany, S.B. Ocean, E.B. Both legs	764 309 1073	$33.0 \\ 69.3 \\ 43.4$	$4.2 \\ 12.3 \\ 6.5$
6. Volume density (1022) Timing plan D; 6/20/51	Alemany, S.B. Ocean, E.B. Both legs	$749 \\ 276 \\ 1025$	$27.8 \\ 66.3 \\ 38.1$	$2.6 \\ 11.2 \\ 4.9$
7. volume density (1022) Timing plan E; 10/10/51	Alemany, S.B. Ocean, E.B. Both legs	703 279 982	$27.9 \\ 68.8 \\ 39.5$	$\begin{array}{c} 2.9\\14.8\\6.3\end{array}$

TABLE 13

STOPPED-TIME DELAY IN OFF-PEAK HOURS, COMPARING FIXED-TIME COORDINATED THMING WITH NON-COORDINATED ACTUATED CONTROLLERS Alemany and Ocean, San Francisco, 1951–1952

9;45 a.m.-3:00 p.m.

Controller and Timing Plan	Street	Volume in Veh/Hr	Percent Stopped	Delay in Seconds per Total Veh.
1. Fixed-time, coordinated for progressive movement on Alemany. 65 Sec. cycle with 37 sec. green on Alemany				
15 15-min. periods, 1/16/52	Alemany, S.B. Ocean, E.B. Both legs	391 211 602	$14.8 \\ 63.5 \\ 31.8$	$\begin{smallmatrix}1.1\\12.8\\5.2\end{smallmatrix}$
 Semi-actuated Phase A: 50 sec. min.; Phase B: 10 + 5, max. 25; 14 15-min. periods, 8/22/51 	Alemany, S.B. Ocean, E.B. Both legs	523 209 732	$24.9 \\ 83.3 \\ 41.5$	$\begin{array}{c} 2.9\\ 25.2\\ 9.1 \end{array}$
 Full actuated (804) Phase A: 13 + 5, max. 70; Phase B: 10 + 5, max. 45; 15 15-min. periods, 7/11/51 	Alemany, S.B. Ocean, E.B. Both legs	492 183 675	$31.5 \\ 58.5 \\ 38.8$	$3.3 \\ 8.3 \\ 4.6$
4. Volume density (1022) Timing plan D; 20 15-min. periods, 6/20/51	Alemany, S.B. Ocean, E.B. Both legs	498 215 713	$27.9 \\ 66.5 \\ 39.6$	$2.6 \\ 8.9 \\ 4.5$

on Alemany Boulevard which were less than half of those resulting from the other types of signal control, for both peak-hour and offpeak traffic conditions. The volume-density method of providing coordinated control apparently was not nearly as effective in reducing delay as was the fixed-time progressive timing for the conditions existing at the intersections along Alemany Boulevard.

A summary of the stopped-time delay occurring at all four legs of the intersection at Ocean Avenue is shown in Table 14 for both coordinated fixed-time and volume density control. It is readily apparent that the delay

TRAFFIC AND OPERATIONS

Controller and Timing Plan	Street	Volume in Veh/Hr	Percent Stopped	Delay in Seconds per Total Veh.
Peak hot	ır: 4;30–5:30 p.m.			<u> </u>
 Fized-time, coordinated for progressive movement on Alemany 1/17/52 Volume density, not coordinated with other signals 10/10/51 	Alemany, S.B. Alemany, N.B. Ocean, E.B. Ocean, W.B. Four legs Alemany, S.B. Alemany, N.B. Ocean, E.B. Ocean, W.B. Four legs	2164 567 370 312 3413 1670 671 342 307 2990	8.0 23.8 67.3 67.9 22.5 27.9 26.4 66.7 71.0 36.4	$1.1 \\ 1.6 \\ 14.8 \\ 15.3 \\ 4.0 \\ 3.6 \\ 2.8 \\ 17.4 \\ 18.5 \\ 6.5 \\ 17.4 \\ 18.5 \\ 18.5 \\ 17.4 \\ 18.5 \\$
Intermediate	volumes: 3:00-4:30 p.m.	<u>_</u> _		
 3. Fized-time, coordinated for progressive movement on Alemany 1/17/52 4. Volume density, not coordinated with other signals 10/10/51 	Alemany, S.B. Alemany, N.B. Ocean, E.B. Ocean, W.B. Four legs Alemany, S.B. Alemany, N.B. Ocean, E.B. Ocean, W.B. Four legs	684 567 297 179 1727 633 599 287 203 1722	$\begin{array}{c} 10.7\\ 26.3\\ 62.3\\ 67.0\\ 30.5\\ 30.0\\ 30.1\\ 69.7\\ 64.5\\ 40.8 \end{array}$	$\begin{array}{c} 0.9\\ 1.6\\ 13.1\\ 14.9\\ 4.7\\ 3.3\\ 3.2\\ 14.2\\ 11.6\\ 6.0\\ \end{array}$

TABLE 14 STOPPED-TIME DELAY FOR FOUR LEGS ON AN INTERSECTION, COMPARING TWO TYPES OF TWO-PHASE SIGNAL TIMING Alemany and Ocean, San Francisco, 1951–1952

to traffic on Alemany Boulevard was lower for both directions of movement under the fixedtime, progressive-timing system than when using volume-density traffic-actuated controllers.

Effect of Timing: Although time did not permit measuring delay for all possible dial settings, the results in Tables 10 to 14 have been summarized separately for each setting of the timing dials so as to permit some comparison of the effect of timing plans. For example, the timing of the semi-actuated controller at Alemany and Santa Rosa on March 28, 1951 (Timing Plan 3 of Table 10) differed from that used on March 21, 1951 (Timing Plan 2 of Table 10) by providing a longer Phase-A green, and a lower minimum initial interval for the side street. As would be expected, the delay to vehicles on Alemany Boulevard decreased, while delay to side-street traffic increased. Total stopped-time delay for the two legs combined decreased also.

Considerable time was spent in attempting to adjust the timing of the volume density controllers so as to provide more efficient control. At Ocean Avenue, Timing Plan D (See Tables 11 and 12) appeared to be the most effective of the three volume-density timing plans in minimizing delay. It is possible, of course, that other timing plans might have reduced delay still further, or that delay might have been lower with detectors located at a different distance from the intersection.

Portola and Vicente Study

Studies of stopped-time delay were also made at the intersection of Portola and Vicente in San Francisco in 1954. In this study, the "necessary" delay to vehicles on Portola Drive was recorded separately from "unnecessary" delay. Two fixed-time and two semiactuated timing plans were investigated, as shown in Table 15.

The results for off-peak traffic-volume conditions indicate that there was no appreciable difference in average stopped-time delay for semi-actuated as compared with fixed-time signals for the timing plans used at this location. However, the percent of the delay which could be classed as "unnecessary" was cut

					Stopped-T	ime Delay
	Controller and Timing Plan	Street	Volume in Veh/Hr	Percent Stopped	Total-sec. per veh.	Percent ''unne- cessary''
1.	Fixed-time, 40 sec. cycle 21 sec. gr. on Portola; 13 sec. gr. on Vicente; 8 15- min. periods, 7/28/54	Portola, E.B. Vicente, S.B. Both less	428 112 540	43.9 60.7 47.4	3.7 8.2 4 7	18.5
2.	Fixed-time, 55 sec. cycle 34 sec. gr. on Portola; 15 sec. gr. on Vicente; 6 15- min. periods, 7/28/54	Portola, E.B. Vicente, S.B. Both legs	519 103 622	29.5 76.4 37.3	3.0 14.9 5.0	22.1
3.	Semi-actuated 30 sec. min. on Portoła; 10 sec. min. on Vicente and ped. timer; 18 15-min. periods, 7/29/54	Portola, E.B. Vicente, S.B. Both legs	468 114 582	27.4 71.9 36.1	2.3 15.6 4.9	11.3
4a.	. Semi-actuated 28 sec. min. on Portola; 12 sec. min. on Vicente and ped. timer; 8 15-min. periods, 9/2/54	Portola, E.B. Vicente, S.B. Both legs	456 149 605	30.3 65.1 38.8	2.8 13.8 5.5	8.7
4b.	Semi-actuated Same timing as plan 4a, above; 8 15-min. periods, 9/15/54	Portola, E.B. Vicente, S.B. Both legs	559 138 697	31.3 70.3 39.0	2.9 12.8 4.9	10.6 —

TABLE 15 STOPPED-TIME DELAY IN OFF-PEAK HOURS FOR FOUR SIGNAL TIMING PLANS Portola and Vicente Avenue, San Francisco, 1954

almost in half when using semi-actuated signal timing. The percent of green time which was classed as "unnecessary" was cut to less than half, as shown in Table 16.

STUDIES AT A LOW-VOLUME INTERSECTION

Stopped-time delays were obtained at the intersection of 47th and Cutting in Richmond, California, during the summer of 1954. Table 17 shows a comparison of results for both offpeak and intermediate traffic volumes, for both fixed-time and semi-actuated controllers. Traffic volumes in the off-peak hour are below those normally warranting a fixed-time traffic signal.

Delay was found to be somewhat lower when using the semi-actuated controller, with substantial reductions in "unnecessary" delay in the off-peak hours, as compared with the fixed-time control.

EFFECT ON DELAY OF DEGREE OF SATURATION

The Road Research Laboratory in England has utilized simulators and electronic computors in studying the relation between stopped-time delay and the degree of saturation of the entering volume, for the case of the fixed-time signal (6). This laboratory has developed a semi-empirical equation (7) for relating delay to the degree of saturation, as follows:

TABLE 16 PERCENT OF SIDE-STREET GREEN CLASSED AS UNNECESSARY Portola and Vicente, San Francisco, 1954

Controller and Timing	Vicente Green as Percent of Cycle	Percent of Vicente Green, Unnecessary
1. Fixed-time (off-peak)		
40 sec. cvcle	33.5	21.1
55 sec. cvcle	27.0	19.9
2. Semi-actuated (off-peak)		
10 sec. min. on Vicente	21.7	9.7
12 sec. min. on Vicente	25.1	6.2
3. Semi-actuated (peak)		
12 sec. min. on Vicente	28.2	1.7

$$d = \frac{.45C(1-g)^2}{1-gx} + \frac{1620x^2}{q(1-x)}$$

- where d = Average delay in seconds per vehicle in the approach to the intersection.
 - C = Cycle length in seconds.
 - g = The proportion of the cycle which is effectively green for the particular phase.
 - q = Volume in vehicles per hour, arriving at random.
 - s = Volume at saturation in vehicles per hour.
 - x = Degree of saturation, or ratio of actual volume to the maximum volume which can be passed through the intersection, given by x = q/gs.

	Street	Volume in Veh/Hr	Percent Stopped	Stopped-Time Delay	
Controller and Timing Plan				Total sec. per veh.	Percent "unne- cessary"
()ff-peak hours	·			
 Fixed-time, not coordinated 50 sec. cycle with 25 sec. gr. on Cutting; 14 15-min. periods, 8/12/54 Semi-actuated (505) Phase A: 22 sec. min.; Phase B: 9 + 4, 20 sec. max.; no ped. timer; detector 70' from curb; 5 15-min. periods, 8/17/54 Semi-actuated (505) Same timing; detector 80' from curb; 13 15-min. periods, 8/18/54 	Cutting, E.B. 47th, N.B. Both legs Cutting, E.B. 47th, N.B. Both legs Cutting, E.B. 47th, N.B. Both legs	161 44 205 181 47 228 143 38 181	$\begin{array}{c} 32.3\\ 54.5\\ 37.1\\ 27.6\\ 72.3\\ 36.8\\ 21.7\\ 57.9\\ 29.3\\ \end{array}$	$\begin{array}{c} 3.0\\ 7.7\\ 4.0\\ 2.1\\ 9.0\\ 3.5\\ 1.7\\ 5.8\\ 2.5\\ \end{array}$	64.1 35.2 52.2 35.6 21.0 27.9 42.9 26.1 34.7
Higher-volu	1me hour: 4:00-5:0	00 p.m.			_
<i>Fixed-time</i> , not coordinated 50 sec. cycle with 25 sec. on Cutting; 8/12/54	Cutting, E.B. 47th, N.B. Both legs	342 152 494	$27.8 \\ 56.6 \\ 36.6 \\ 36.6 \\ \end{array}$	2.8 6.7 4.0	$41.9 \\ 14.2 \\ 27.7$
 Semi-actualed (505) See Plan 2, above; 8/17/54 Semi-actualed (505) See Plan 3, above; 8/18/54 	Cutting, E.B. 47th, N.B. Both legs Cutting, E.B. 47th, N.B. Both legs	364 146 510 303 162 465	28.674.741.840.657.446.5	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$25.9 \\ 15.6 \\ 19.2 \\ 21.3 \\ 16.2 \\ 18.6$

TABLE 17 STOPPED-TIME DELAY AT A LOW VOLUME INTERSECTION SEMI-ACTUATED VS FIXED-TIME CONTROL 47th and Cutting Blvd., Richmond, California



Figure 8. Typical fixed-time delay curve of Road Research Laboratory. (1)

In Figure 8 there is a typical delay curve for one approach to a fixed-time signal, showing the relation between travel-time delay per vehicle (as a percent of cycle length), and the degree of saturation. The points on the curve represent results obtained by utilizing the simulator. The curve itself was derived from the above equation. Note that, as the degree of saturation approaches 1.0 (or 100 percent), the delay increases rapidly.

The traffic volume at which the delay increases sharply depends primarily on the capacity of the approach, expressed in terms of the product of the saturation flow and the effective green. The formula assumes that saturation flow remains constant, whereas actually the saturation flow may vary according to the time of day or changes in traffic conditions. Considerable variations in delay would thus be expected when traffic volumes approach the capacity of an intersection approach.

The above formula has been used to compute the delay at several intersections in the San Francisco area to determine whether computed results are similar to results obtained in field studies. The computed values for off-peak hours generally checked the observed values within 25 percent; the differences for the peak-hour condition sometimes exceeded 25 percent. The observed values are lower than computed values for the case of progressive timing of signals.

The comparison of actual vs. computed de-

T	Volume in VPH		TOT IN T	Degree of	Delay in Sec. Per Veh.		
Intersection Approach	Actual flow	Saturation flow	Effective green	Saturation	Computed	Observed	
I	0	ff-peak—2:15-3:1	5 p.m., 8/26/53. 55	sec. cycle	···		
		1	percent	percent			
Portola, W.B Woodside O'Shaughnessy	611 304 139	4700 3000 3400	$\frac{38}{29}$ $\frac{21}{88}$	34 35 19	$11.3 \\ 14.7 \\ 16.6$	$9.3 \\ 15.4 \\ 19.4$	
		Peak-4: 45-5: 15	p.m., 8/26/53. 80 s	ec. cycle			
Portola, W.B. Woodside O'Shaughnessy	1670 440 580	4700 3000 3400	51 22 21 $-$ 94	70 67 81	$14.9 \\ 30.9 \\ 36.7$	17.8 29.9 52.3	
		Peak—4: 45-5: 15 p	o.m., 9/15/53. 100 s	sec. cycle	· · · · · ·		
Portola, W.B Woodside O'Shaughnessy	$\begin{array}{c} 1982\\ 424\\ 684\end{array}$	4700 3000 3400		74 64 112	16.0 36.3 Infinite	12.7 29.0 223.5	

TABLE 18 COMPARISON OF COMPUTED VS OBSERVED DELAYS USING ROAD RESEARCH LABORATORY FORMULA (6) Portola, Woodside, and O'Shaughnessy, San Francisco

lay values for one intersection is shown in Table 18. These results for O'Shaughnessy Avenue serve to demonstrate the effect of slight changes in volume and proportion of green on delay for peak-hour conditions. The volume during the peak hour on one day (September 15, 1953) was 20 percent greater than on August 26, 1953, and the effective green decreased from 21 percent of the cycle length to 18 percent. These slight changes increased the degree of saturation from 81 percent to over 100 percent, and delay increased drastically, for both computed and observed values, as shown in the table.

These results demonstrate the critical problem of setting the timing of three-phase, fixedtime signals for near-capacity conditions, and the disastrous effect of variations in arrival rates. It is difficult to time such signals for efficient operation at near-capacity conditions, if there are fluctuations in the proportion of traffic arriving on the intersecting legs during different portions of the peak hours. Such fluctuations can be taken into account automatically by vehicle-actuated signals, since the proportion of effective green allocated to each phase can change in accordance with the change in approach volumes. CONCLUSIONS AND RECOMMENDATIONS

- 1. Field measurements of stopped-time delay can be used as a basis for comparing vehicular delay under different types of control at signalized intersections. However, due to the many variables (signal timing, day-to-day fluctuations in traffic, parking, capacity, time of year, etc.), it is difficult to isolate the effects of small changes in timing, without extensive field investigations.
- 2. Delay meters which accumulate vehicleseconds of stopped time can give reliable results under conditions in which the number of vehicles accumulated at any time can be estimated with reasonable accuracy by the operator. The sampling method of determining stopped-time delay is simpler than the delay-meter technique and gives equally reliable results under the conditions tested. The time interval between observations must be selected to avoid repetitive sampling in the same parts of the signal cycle.
- 3. Vehicle-actuated traffic signals are better able to accept short-term fluctuations in traffic volume than fixed-time signals.

The percent of delay which can be classed as "unnecessary" was cut substantially when using actuated signals at locations where signal coordination is not a factor.

- 4. The following conclusions apply at threephase signalized locations where interconnection with nearby signals is not a factor.
 - a. At intersections with actuated control and some pedestrian movements, the use of pedestrian timers can substantially reduce vehicular delay, especially at off-peak hours.
 - b. The use of an overlap sequence in the timing of three-phase signals with heavy left-turn movements from only one direction can materially reduce delay under both off-peak and peakhour conditions, provided the volume of vehicular traffic from the opposing left-turn movement is sufficiently light to permit one through- and one left-turn movement to overlap a substantial portion of the time.
- 5. When signalized intersections are spaced so that the signals can be timed for progressive movement, the use of fixed-time coordinated timing can cut delay substantially, as compared with fixed-time or traffic-actuated signals with no coordination in the timing.
- 6. More study should be given to such problems as:
 - a. The use of traffic simulators and computors for studying in the laboratory the effects of small differences in timing of signals and placement of detectors.
 - b. The relative delay under different types of coordinated traffic signal systems.

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