

The future of roads.

NCHRP 20-24(128) Cooperative Automated Transportation June 28, 2021

The Future of Roads



CARS ARE GETTING SMARTER

Vehicles with increasing ADAS¹ capability are reaching scale

Accelerating the Benefits of Autonomy



Cavnue enables...



Anticipated ADAS Model Launches			Intro year	Models by 2025 ¹
	Ford	Ford Co-Pilot 360 2.0	2020	- 11
	<u>gm</u>	General Motors Super Cruise	2020	22
	7	Tesla Autopilot	2020	5

2020

2020

2021

Volvo

Nissan

Toyota

Pilot Assist

Volkswagen

Traffic Jam Assist

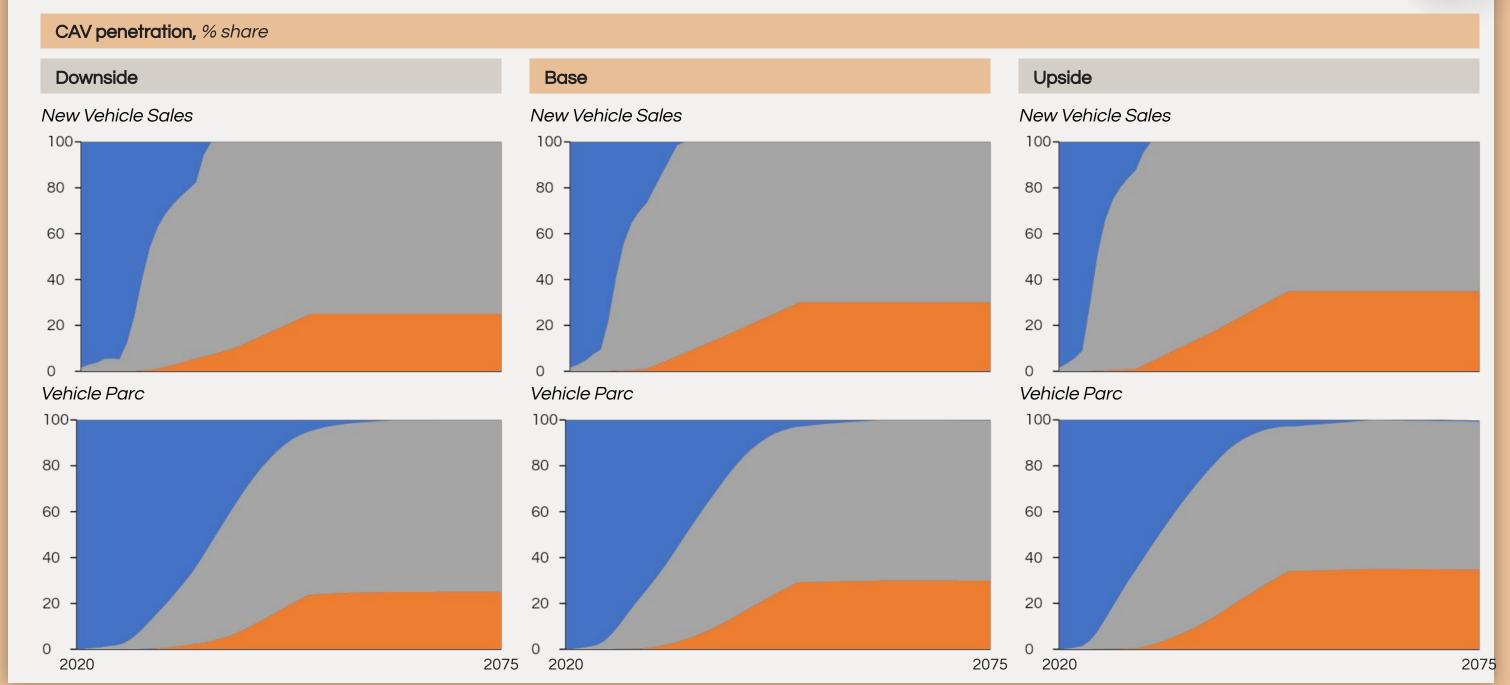
ProPilot Assist 2.0

SafetySense 2.5

Penetration of Sales and Parc by CAV capability



<L2 Capable L2+ Capable L4 Capable</p>



The Future of Roads



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ROADS HAVE NOT KEPT UP

Road infrastructure is woefully inadequate to achieve these vehicles' full potential

Today's roads present a complexity problem to AVs

Operational design domain

Environment



Weather



Lighting



Road condition

Road configuration



Ramp

Tunnel

Shoulder

Crosswalk

Traffic lights

Bike lane



Bridge

Interchange



Roundabout



Stop sign

Driveway



Unprotected



One-way



Crosswalk



Parking lot



Garage

Road actors







EMS



School bus



Motorcycle



Bicycle



Pedestrian



Wheelchair



Objects

Driving maneuvers



Follow lane



LH turn



RH turn



Lane change



Merge



// Pull over





Swerve



Emergency

"Scene" risks

"Scenario" risks

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SMART CARS NEED SMART ROADS

The future of roads will be safer and more efficient



Creating Value for All Stakeholders



Drivers & Passengers

Improve safety, give time back, & expand access to transportation



OEMs / AV **Companies**









Enhance existing ADAS offerings and ship fully autonomous STELLANTIS systems faster















DOTs & **Policymakers**

Save lives, increase throughput, and meet environmental goals



Road Operators

Drive operational efficiencies, provides new insights & new revenue sources



Cavnue Management Team





Tyler Duvall Chief Executive Officer

Nationally recognized leader in transportation

McKinsey & Company







Jaime Waydo **Chief Technology Officer**

Former Waymo Chief Systems Engineer; most recently led Apple's autonomous systems efforts









Nicole Nason Chief Safety Officer, **Head of External Affairs**

Former Administrator of both **FHWA and NHTSA**









Mark de la Vergne **Project Development**

Former mobility lead for City of Detroit







Dave Clifford Strategic Innovation and **Analytics**

Former head of AI/ML at General Motors







Dino Nardicchio Automotive & AV Partnerships

Former Global VP of R&D Magna International







Pete Kenny General Counsel

Former multi-vertical legal lead at HP and VP/DGC at Perspecta

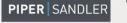


▶X DXC.technology



David Kiley Business Development

Former managing director of municipal finance at Piper Sandler







Hardware Engineering

Former lead of Google AR/VR hardware and Hardware Lead at Google







Michigan Project Overview



Launch

• Launched Cavnue in August 2020 in Michigan



 Announced flagship project with key partners in government and private sector



Bill Ford and Mayor Duggan at announcement

Co-development

• Signed exclusive Master Developer agreement with Michigan Department of Transportation



Controls the right of way



Funder and Master Developer

Co-lead

Management committee

Working groups

• Kicked off process to scope project



Technology and infrastructurePrototyping / requirements



Policy and regulation Legislative / regulatory needs



Community engagement
Public support + econ dev



Finance + Operations
Viable project business case



Planning + Design
Viable project business case

Robust network of partners

• Engaged a broad / growing set of local partners

























Stage

Initial Discussions

Feasibility Analysis

Execution

Agreement by late 2021

OEM Partnerships



Cavnue helps OEMs...

- Ship + scale faster. There has been \$100B+ invested in AV / ADAS to date without clear ROI timeline.
- Ensure a single standard. Multiple smart infrastructure architectures adds complexity to integration.
- •Provide value-added services for all users. Lane-level monitoring on Cavnue corridors improves overall road-user experience, beyond CAV benefit.



























"Providing safe, well-maintained infrastructure that is consistent (both internally and with other roadways) and avoids deviations (in road design, signage, traffic signals, and other key elements) is a critical part of enabling advanced ADAS systems and forward-looking autonomy."

The Roads of the Future



Cavnue is integrating hardware and software to ensure that the roads of the future are safer and more efficient



Roadside Equipment

Physical Layer

Road design and supporting physical infrastructure



Digital infrastructure underpinning the Virtual Twin











Virtual Twin

Coordination Layer

Data aggregation and orchestration in a Virtual Twin





Operational Layer

Tolling + Enhancement of public transit, shared mobility, and freight





Infrastructure & Learning

Underpinning Tech

Software infrastructure and algorithms

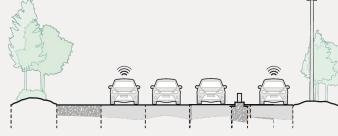




Technology Development Timeline

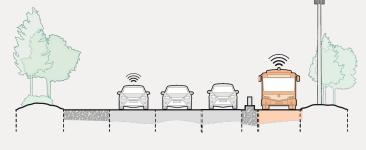
Cavnue's deployment framework provides flexibility and optimized operations both during early stages of Level-2+ (L2+) introduction and as CAVs reach higher penetration levels.

From 2022: Cavnue Tech
Deployments

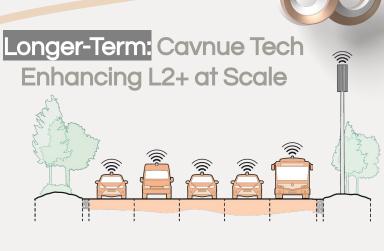


Deploy Cavnue hardware and software in mixed traffic conditions to create a safer road, reduce valuable edge cases and create digital enhancements.

From 2023+: Cavnue Tech
Accelerating L2+



As L2+ CAV utilization increases, deploy a CAV lane that allows for mixed traffic operations but provides hands-off/eyes-off experience to CAV vehicles.



As CAV penetration continues to rapidly increase, additional features of Cavnue's technology enable enhanced CAV operations such as coordinated driving and platooning.

1950s to Today: Regular Vehicles on Regular Roads

